The Extended Standard Product 3 Orbit Format (SP3-d)

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INTRODUCTION

The SP3-d format adds three extensions to the previous SP3-c format: the maximum number of satellites is increased from 85 to 999, there are now an unlimited number of comment records allowed in the header, and the maximum length of each comment record has been increased from 60 characters to 80 characters.

The need for the first change, getting past the 85 satellite limit, was long anticipated but has been accelerated recently by work done for the Multi-GNSS Experiment (MGEX), an effort that was undertaken within the International GNSS Service (IGS) to explore and promote the use of new navigation signals and methods (Montenbruck et al. 2013). One product being discussed by the IGS Multi-GNSS Working Group (MGWG) is a broadcast ephemeris containing most of the existing Global Navigation Satellite System (GNSS) and Satellite-Based Augmentation System (SBAS) satellites. The number of satellites to be included is already over 85. In addition to being offered as a RINEX Navigation Message File, it will also be made available as an SP3-d file for those that might prefer using the broadcast orbits in that format (Montenbruck, 2013).

The second and third changes have also been considered previously. In the past, the various IGS Analysis Center Coordinators who oversee the creation of the IGS combined orbit products have complained about trying to adequately describe the combined orbits using only the four comment lines allowed in SP3-c. If a change is made to allow an unlimited number of comment lines, to increase the amount of comment space available, it also makes sense to go ahead and increase the length of each comment line from 60 characters to 80 characters. Most of the ephemeris data records found after the header are already 80 characters wide, as allowed in SP3-c.

Over the past several years there have been other suggestions/requests for additional features such as: 0.1-millimeter (or better) resolution in satellite coordinates, irregularly-spaced epochs for kinematic LEO orbits, use of both NAVSTAR and PRN ID numbers to uniquely identify each satellite, and the use of quaternions to represent satellite attitude. These features have been included in a proposed format called The ORBit EXchange (ORBEX) format (Hilla, 2010) which is based on a more flexible, expandable design similar to the SINEX format (an idea first proposed by Gerd Gendt). While there are many users who are looking forward to the added features in ORBEX, it is understandable that many of these same users are not looking forward to the work involved in jumping to a completely new format. There is still a lot of work to be done to pare down the current ORBEX Draft Version, and to decide how best to balance brevity versus modularity for ORBEX (i.e., is it better to combine several different types of metadata in one block to save space, or to separate the metadata into separate blocks even if this

1 #dP2013 4 2 ## 1734 2592 3 + 140 G01 4 + G18 5 + R03 6 + R20 7 + E13 8 + E30 9 + C17 10 + C34 11 + S33 12 ++ 00 13 ++ 00 14 ++ 00 14 ++ 00 15 ++ 00 16 ++ 00 17 ++ 00 16 ++ 00 17 ++ 00 18 ++ 00 19 ++ 00 20 ++ 00 20 ++ 00 21 %c M cc GPS 22 %c cc cc ccc 23 %f 1.250000 24 %f 0.000000 25 %i 0 0 26 %i 0 0 26 %i 0 0 27 /* Note: Thi 28 /* might loc 29 /* lite posi 30 /* I=IRNSS,S 31 /* http://ig 32 * 2013 4	3 0 0 0.0000000 200.0000000 900.000 200.00000000 900.000 200203G04G05G06G07G03 20192203212223324621 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 20102203C04C05C06C0 2010203C04C05C06C0 2010203C04C05C06C0 2010203C04C05C06C0 2010203C04C05C06C0 2010203C04C05C06C0 2010200000000 20100000000000 2010000000000	96 ORBIT WGS 000000 56385 0.00 8G09G10G11G12G130 5G26G27G28G29G300 OR11R12R13R14R15F 3E04E05E06E07E08F 0E21E22E23E24E25F 7C08C09C10C11C120 4C25C26C27C28C290 3I04I05I06I07S205 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	S84 BCT MGEX D000000000 G14G15G16G17 G31G32R01R02 R16R17R18R19 E09E10E11E12 E26E27E28E29 C13C14C15C16 C30C31C32C33 S24S27S28S29 0 0	3-d header nd SBAS satel- ou,J=QZSS, ne website:
33 PG01 5783. PG02 -22412. PG03 10114. PG04 -24002. PG05 -15087. PG06 13855.	206741 -18133.044484 401440 13712.162332 112309 -17446.189044 325710 4250.313148 153141 8034.886396 140409 -11053.269706	-18510.756016 528.367722 16665.051308 -11163.577756 20331.626539 19768.346019	12.734450 425.364822 189.049475 179.333612 -390.251167 289.556712	
PS28 5169. PS29 -32240. PS33 -5555. PS35 -28749. PS37 -34534. PS38 -12548. * 2013 4	591020 41849.037979 432088 27155.480094 490565 -41739.269117 533445 -30836.454809 904566 24164.610955 655240 -40249.910397 3 0 15 0.00000000	17.421140 -12.156456 2093.250932 -4.729472 29.812840 -3.521920	0.170452 0.101500 -0.199099 -0.008333 0.299420 -0.027787	
* 2013 4 PG01 4340. PG02 -22187. PG03 9785. PG04 -24642. PG05 -13667. PG06 13696.	3 23 45 0.0000000 761149 -17469.395805 015530 13877.264416 535610 -18824.396329 374460 4816.578416 233808 8977.038381 828033 -12657.020030	-19521.652181 2583.141886 15333.698561 -9365.337848 20922.734874 18869.219517	13.021579 425.527461 189.465625 180.261632 -390.371011 288.240920	
PS28 5172. PS29 -32238. PS33 -5561. PS35 -28751. PS37 -34533. PS38 -12549. EOF	029472 41849.075534 862503 27158.965634 856798 -41736.409969 361488 -30835.144592 867549 24170.548454 851291 -40249.647004	17.353884 -13.223188 2123.557039 -6.745702 28.300343 -4.471664	0.346319 0.179982 0.009913 -0.006819 -0.223601 -0.003125	

Example 1. An SP3-d file with 140 satellites and 5 comment lines.

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Example 2. A GPS-only SP3-d file with all record types (P, EP, V, EV).

1234567890111213141516	#dV ## + + + + + + + + + + + + + + + * * * *	2001 1126 26 Gcc cc	8 259 G0 G2 C GP	8 200. 1G02 3G24 0 0 0 0 7 8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 (0000(GO36 G256) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0. 00000 00460 00 0 0 0 0 0 0 0 0 0 0 0	0000 5606 7628 0 (0 0 (0 6 7 7 7 0 (0 0 (0 0 (0 0 (0 0 (0 0 (0 0 (00000 000.0 56076 36296 0 0 0 0 0 0 0 0 0 0 0 0 0	00000 0860 3063 0 0 7 7 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	19 0000 09G1 1 0 0 7 7 0 0 0 7 7 0 0 0 0 0 0 0 0 0	2 OF 521 0G11 0 C 0 C 0 C 0 C 0 C 0 C 0 C 0 C 0 C 0 C	RBIT L29 (LG130 (0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	IGS 0.00 G14G 0 0 0 7 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	97 H 0000 17G1 0 0 0 0 8 0 0 0 0 0 0 0 0 0 0 0 0 0 0	LM 0000 8G2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	MGEX 0000 0G21 000 000 000 000 000 000 000 000 000 0					
17 18 19 20 21 22 23 24 25	%i %i /* / /* /* (* PG0: EP	0 0 AN E NOTE CCCC 2001 1 -1 5	EXAMP THE CCCCC CCCCC - 8 .1044	0 0 2LE L 2CCCC 2CCCC 8 - 805 55	0 0 JLTRA EDIC CCCCC 0 0 5800 55	0 0 A RAF CTED CCCCC CCCCC CCCCC 0 0.	PID (DATA CCCC CCCC 000(75.6 222	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	, GF AGS CCCCC CCCCC 0 2 4567	0 0 FOR CCCC CCCC 2192 7 -1	NLY THE CCCC CCCC 9.41 2345	0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	ST E CCCC CCCC 0 599	0 0 POCH CCCC CCCC 189 9999	(I CCC CCC .16	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		NS 76 CCCCC CCCCC 18 1	6 and CCCCC CCCCC 18 21 21	80) ccccc ccccc 9 -123	cccc cccc
26 27	VG0: EV PG0: EP VG0: EV PG0: EV VG0: EV VG0: EV	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0298 2 2593 9481 9335 5 2497 2 6148	22 55 55 .923 22 .606 55 .392 22 22 .392)364 22 3500 55 3808 22 5450 55 2894 22 5900	-184 101 -258 -219 -84	62.0 111 222 32.0 111 52.9 222 82.2 111 82.2 111	04480 123 32765 123 55256 123 99075 123 26029 123	44567 0 -2 4567 4567 4567 4567 4567 8 4567	138 2035 2-1 -727 2-1 1162 2-1 2623 2-1	1.38 2345 4.55 2345 7.16 2345 4.35 2345 0.34 2345 2345 2345 2345	3768 567 5440 567 5005 567 5015 567 1845 567	5 123 599 123 0 599 9 123	-4 4567 -55 9999 8 4567 54 9999 5 4567 617	.53 1.97 .80 1.75 .62	4317 2345 6000 	14 67 18 30 14 67 18 30 14 67 18	14 1 1234 18 1 14 1 1234 18 1 14 1 1234 18 1	$14 \overline{19}$ 4567 18 21 14 19 4567 18 21 21 14 19 4567 18 21 14 19 4567 18 21	1 1234 9 -1230 1 1234 9 -1230 1 1234 9	4567 0000 4567 0000 4567
	EP VG0 ⁴ EV PG0 ¹ EP VG0 ¹ EV	$\begin{array}{c} + & -1 \\ 5 \\ 4 \\ 5 \\ 5 \\ 5 \\ 5 \\ 2 \\ 2 \\ 5 \\ 2 \\ 2 \\ 2$	2859 2859 3454 392 2	55 768 22 .631 55 .255 22	55 55 55 22 22 2450 55 5680 22	-85 209 123	222 524.5 111 556.3 222 67.0 111	123 53898 123 53370 123 53370 123 58693 123	4567 3 -1 4567 0 4567 7 -2 4567	2940 2 -1 506 2 937 2 937 2 795 2 795 2 1	2345 3.22 2345 6.99 2345 5.76 2345	567 29099 567 567 567 567	599 5 123 599 7 123	9999 -3 4567 308 9999 -13 4567	.99 .29 .95 .60 1	2980 2345 6400 - 0595 2345	30 14 67 18 30 14 67	14 1 1234 18 1 14 1 1234	21 14 19 4567 18 21 14 19 4567	-1230 1 1234 9 -1230 1 1234	0000 4567 0000 4567
	* PG02 EP VG02 EV PG02 EP VG02 EV	2001 1 -1 5 1 2 2 -1 5 2 - 2 - 2	- 8 1044 5 0298 2 2593 5 9481 2	9 2 .805 55 .880 22 .593 55 .923 22	23 45 5800 55 0364 22 3500 55 8808 22	5 0. -104 -184 101 -258	0000 222 62.0 111 .70.3 222 32.0 111	00000 57235 123 04480 123 32765 123 55256 123	0 2 4567 4567 4567 4567 4567	2192 7 -1 138 7 1 2035 7 -1 -727 7 1	9.41 2345 1.38 2345 4.53 7.16 2345	L8200 567 3768 567 34400 567 50050 567) 599 123) 599 6 123	189 9999 -4 4567 -55 9999 8 4567	.16 .53 .97 .80 1	3300 - 4317 2345 6000 - 1258 2345	18 30 14 67 18 30 14 67	18 1 14 1 1234 18 1 14 1 1234	18 21 21 14 19 4567 18 21 21 14 19 4567	9 P -123(1 1234 9 P -123(1 1234	P 0000 4567 P 0000 4567
	PG3 EP VG3 EV PG3 EP VG3 EV EV EOF	$\begin{array}{ccc} 0 & -2 \\ 5 \\ 0 & -1 \\ 2 \\ 1 & 1 \\ 5 \\ 1 & -1 \\ 2 \end{array}$	3592 3996 2 7353 5 6984 2	. 378 55 .847 22 .533 55 .306 22	3250 55 7785 22 3200 55 5646 22	13 -69 151 -24	395.(222 945.(111 51.1 222 24.9 111	04980 123 56548 123 10570 123 91333 123	0 -1 4567 4567 4567 4567 4567	L252 2590 2590 2385 2-1 2396 2396 2396	4.03 2345 8.19 2345 1.53 2345 9.27 2345	8710 567 99568 567 84050 567 77673 567) 599 123) 599 7 123	461 9999 4567 -1 9999 -14 4567	.97 .36 .84 .37 1	2900 - 4488 2345 1700 - 1692 2345	18 30 14 67 18 30 14 67	18 1 1234 18 1 14 1 1234	18 21 21 14 19 4567 18 21 21 14 19 4567	9 P -123(1 1232 9 P -123(1 123	P 0000 4567 P 0000 4567

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results in a slightly more verbose file). In the meantime, the MGWG within the IGS needs SP3-d now to get past the 85 satellite limit.

One final note is needed regarding multi-constellation orbit files. Just because one can put GNSS satellites from multiple constellations into the same SP3-c or SP3-d file, doesn't mean it is always a good idea. For example, non-trivial inter-system timing and orbital reference frame differences currently preclude the IGS from making a rigorous GPS+GLONASS product where the two constellations are truly in the same Time System and in the same Reference Frame. For lower accuracy files (like the MGWG broadcast ephemeris SP3 file mentioned above) these differences in Time System and Reference Frame might be ignored, as long as everyone understands the limitations of such a file.

IMPLEMENTATION CONSIDERATIONS

Each of the record types found in an SP3 header has a unique set of characters in columns one and two. This makes it easy to read through the header, even when the number of lines in the header is dependent on the number of satellites and the number of comment records. For example, for any SP3-d file, the first two records (beginning with "#d" and "##") will always be present. The third through seventh lines will always be present as well. For backwards compatibility, every SP3-d file must always have at least: five satellite ID records (beginning with "+ "), five orbit accuracy records (beginning with "++"), and four comments records (beginning with "/*"); even when the number of satellites is less than 85 (see Example 2). If there are more than 85 satellites, there will be more than five "+ " records and these records can be read in until the first "++" record is encountered. There are 17 satellite IDs on each line, and this fact can be used to compute the indices for loading the satellite IDs into an array if required. The last "+ " line may contain zeroes if the number of satellites (given on line three) is not an even multiple of 17. As a check, the number of satellite IDs read in should match the number of satellites given on line three.

There should always be the same number of "++" records as there are "+ " records, since both record types are dependent on the number of satellites. Again, this fact can be used to check the number of "++" records, which can be read in until the first "%c" record is encountered. After the "++" records, there will always be exactly two "%c", two "%f", and two "%i" records. Columns 10-12 in the first %c record define what time system is used for the date/times in the ephemeris. If estimates of the standard deviations for the satellite coordinates and satellite clock offsets are given, then the first "%f" line will hold the floating point base numbers (e.g., 1.25 for the coordinates, and 1.025 for the clock offsets), see Example 2. See also the text regarding line twenty-three in the section below entitled "DETAILED DISCUSSION OF THE SP3-d FORMAT".

After the second "%i" record is read in, the comment records will follow. These comments can be read in until the first "* " record is encountered (i.e., until the first Epoch Header Record is found). This will mark the end of the header, and the beginning of the actual ephemeris part of the file. Although the number of comment records is theoretically unlimited, users are asked to practice constraint. It was considered to limit the number of comment lines to 40 or 400. However, any such limit would seem somewhat arbitrary. The beauty of the SP3 format is really its compactness, and it would seem to go against the spirit of SP3 to see a file with tens of thousands of comment lines and only 3,200 lines of actual data. Please make your comments brief. One can always include a URL or some other reference that points to other files with additional metadata. This is especially important for any large number of orbit files that will need to be archived.

HISTORY OF THE SP3 FORMAT

For the history of the SP3 format, originally developed by Benjamin W. Remondi, please refer to Appendices A and B at the end of this document.

COLUMN-BY-COLUMN DESCRIPTION OF THE SP3-d FORMAT

Standard Product #3 ASCII SP3 Format Version "d" (see Example 1.)

Columns	Description	Example	Format
SP3 First Line			
Columns $1-2$ Column 3 Columns $4-7$ Column 8 Columns $9-10$ Column 11 Columns $12-13$ Column 14 Columns 15-16 Column 17 Columns 18-19 Column 20 Column 20 Columns 21-31 Column 32 Column 32 Columns 33-39 Column 40 Columns 41-45 Column 46 Columns 47-51 Column 52 Column 53-55 Column 56 Column 57-60	Version Symbol Pos or Vel Flag Year Start Unused Month Start Unused Day of Month St Unused Hour Start Unused Second Start Unused Second Start Unused Number of Epochs Unused Data Used Unused Coordinate Sys Unused Orbit Type Unused Agency	#d P or V 2013 -4 -3 -0 -0 -0 -0.00000000 96 ORBIT WGS84 BCT MGEX	A2 A1 I4 blank I2 blank I2 blank I2 blank F11.8 blank I7 blank A5 blank A5 blank A5 blank A3 blank A3 blank
SP3 Line Two Columns 1-2 Column 3 Columns 4-7 Column 8 Columns 9-23 Column 24 Columns 25-38 Column 39 Columns 40-44 Column 45 Columns 46-60	Symbols Unused GPS Week Unused Seconds of Week Unused Epoch Interval Unused Mod Jul Day St Unused Fractional Day	## 1734 259200.00000000 900.00000000 56385 0.000000000000000	A2 blank I4 blank F15.8 blank F14.8 blank I5 blank F15.13
SP3 Line Three			

Columns 1-2	Symbols	+	A2
Column 3	Unused	_	blank

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Columns 4-6 Column 7-9 Columns 10-12 Column 13-15	Number of Sats Unused Sat #1 Id Sat #2 Id	140 G01 G02	I3 3 blanks A1,I2.2 A1,I2.2
Columns [*] 58-60	Sat #17 Id	G17	A1,I2.2
SP3 Line Four			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #18 Id Sat #19 Id	+ G18 G19	A2 7 blanks A1,I2.2 A1,I2.2
columns 58-60	Sat #34 Id	R02	A1,12.2
SP3 Line Five			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #35 Id Sat #36 Id	+ R03 R04	A2 7 blanks A1,I2.2 A1,I2.2
columns [*] 58-60	Sat #51 Id	R19	A1,I2.2
SP3 Line Six			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #52 Id Sat #53 Id	+_ R20 R21	A2 7 blanks A1,I2.2 A1,I2.2
Columns 58-60	Sat #68 Id	E12	A1,I2.2
SP3 Line Seven			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #69 Id Sat #70 Id	+ E13 E14	A2 7 blanks A1,I2.2 A1,I2.2
Columns 58-60	Sat #85 Id	E29	A1,I2.2

Note: If there are more than 85 satellites, there will be more than just the required five satellite ID ("+ ") records.

SP3 Line Eight			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #86 Id Sat #87 Id	+ E30 C01	A2 7 blanks A1,I2.2 A1,I2.2
Columns [*] 58-60	Sat #102 Id	C16	A1,I2.2
SP3 Line Nine			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #103 Id Sat #104 Id	+_ <u> C17</u> C18	A2 7 blanks A1,I2.2 A1,I2.2
columns 58-60	Sat #119 Id	C33	A1,I2.2
SP3 Line Ten			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #120 Id Sat #121 Id	+ C34 C35	A2 7 blanks A1,I2.2 A1,I2.2
č č Columns 58-60	Sat #136 Id	s29	A1,I2.2
SP3 Line Eleven			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #137 Id Sat #138 Id	+ 	A2 7 blanks A1,I2.2 A1,I2.2
Columns 58-60	Sat #153 Id	0	A1,I2.2
SP3 Line Twelve			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #1 Accuracy Sat #2 Accuracy	+++ 0 0	A2 7 blanks I3 I3
columns 58-60	Sat #17 Accuracy	0	13

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SP3 Line Thirteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #18 Accuracy Sat #19 Accuracy	++- 0 0	A2 7 blanks I3 I3
* Columns 58-60	Sat #34 Accuracy	0	13
SP3 Line Fourteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #35 Accuracy Sat #36 Accuracy	++ 0 0	A2 7 blanks I3 I3
* Columns 58-60	Sat #51 Accuracy	0	13
SP3 Line Fifteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #52 Accuracy Sat #53 Accuracy	++- 0 0	A2 7 blanks I3 I3
* Columns 58-60	Sat #68 Accuracy	0	13
SP3 Line Sixteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #69 Accuracy Sat #70 Accuracy	+++ 0 0	A2 7 blanks I3 I3
* Columns 58-60	Sat #85 Accuracy	0	13
Note: If there are just the req	more than 85 satel uired five orbit ac	lites, there will be curacy ("++") record	more than s.
SP3 Line Seventeen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #86 Accuracy Sat #87 Accuracy	+++ 0 0	A2 7 blanks I3 I3
* Columns 58-60	Sat #102 Accuracy	0	13

SP3 Line Eighteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #103 Accuracy Sat #104 Accuracy	++- 0 0	A2 7 blanks I3 I3
columns 58-60	Sat #119 Accuracy	0	13
SP3 Line Nineteen			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15	Symbols Unused Sat #120 Accuracy Sat #121 Accuracy	++- 0 0	A2 7 blanks I3 I3
columns [*] 58-60	Sat #136 Accuracy	0	13
SP3 Line Twenty			
Columns 1-2 Columns 3-9 Columns 10-12 Columns 13-15 *	Symbols Unused Sat #137 Accuracy Sat #138 Accuracy	+++ 0 0	A2 7 blanks I3 I3
Columns 58-60	Sat #153 Accuracy	0	13
SP2 Line Twenty one			
Columns 1-2	Symbols	%c	۸2
Column 3	Unused		blank
Columns 4-5	File Type	M	A2
Columns 7-8	2 characters		ртапк 42
Column 9	Unused	_	blank
Columns 10-12	Time System	GPS	A3
Columns 14-16	3 characters		DTANK A3
Column 17	Unused	_	blank
Columns 18-21	4 characters	сссс	A4
Column 22 Columns 23-26	Unusea A characters		blank 1
Column 27	Unused	_	blank
Columns 28-31	4 characters	сссс	A4
Column 32 Columns 33-36	Unused 4 characters		blank
Column 37	Unused		blank
Columns 38-42	5 characters	ссссс	A5
Column 43	Unused 5 charactors		blank
Column 49	unused		дэ blank
Columns 50-54	5 characters	ccccc	A5
Column 55	Unused	_	blank



Columns	56-60	5	characters	ccccc

SP3	Line	Twenty	two
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Columns 1-2 Symbols %c	A2
Column 3 Unused _	blank
Columns 4-5 2 characters cc	A2
Column 6 Unused _	blank
Columns 7-8 2 characters cc	A2
Column 9 Unused _	blank
Columns 10-12 3 characters ccc	A3
Column 13 Unused _	blank
Columns 14-16 3 characters ccc	A3
Column 17 Unused _	blank
Columns 18-21 4 characters cccc	A4
Column 22 Unused _	blank
Columns 23-26 4 characters cccc	A4
Column 27 Unused _	рганк
Columns 28-31 4 Characters CCCC	A4 blank
Column 32 Unused _	DIANK
Column 27 Unucod	A4 blank
Columns 28-42 5 characters	01alik 45
Column 42 Unusod	AJ
Columns 44-48 5 characters cocco	10 TAIIK
Column 19 Unused	hlank
Columns 50-54 5 characters ccccc	Δ1αΠΚ Δ5
Column 55 Unused	hlank
Columns 56-60 5 characters ccccc	A5

Α5

SP3 Line Twenty three

Columns	1-2	Symbols	%f	A2
Column	3	Unused	_	blank
Columns	4-13	Base for Pos/Vel	_1.2500000	F10.7
		(mm or 10**-4 mm/se	ec)	
Column	14	Unused	_	blank
Columns	15-26	Base for Clk/Rate	_1.025000000	F12.9
		(psec or 10**-4 pse	ec/sec)	
Column	27	Unused	_	blank
Columns	28-41	14-column float	_0.000000000	F14.11
Column	42	Unused	_	blank
Columns	43-60	18-column float	_0.000000000000000	F18.15

SP3 Line Twenty four

Columns Column Columns Column Columns Column Columns Column	1-2 3 4-13 14 15-26 27 28-41 42	Symbols Unused 10-column Unused 12-column Unused 14-column Unused	float float float	%f _0.0000000 _0.000000000 _0.0000000000	A2 blank F10.7 blank F12.9 blank F14.11 blank
Column Columns	42 43-60	Unused 18-column	float	_0.000000000000000000000000000000000000	blank F18.15

SP3 Lines Twenty	five and Twent	y six	
Columns 1-2	Symbols	%i	A2

Column	3	Unused		_	blank
Columns	4-7	4-column	int	0	I4
Column	8	Unused		_	blank
Columns	9-12	4-column	int	0	I4
Column	13	Unused		-	blank
Columns	14-17	4-column	int	0	I4
Column	18	Unused	_	-	blank
Columns	19-22	4-column	int	0	I4
Column	23	Unused	_	_	blank
Columns	24-29	6-column	int	0	16
Column	30	Unused	_	_	blank
Columns	31-36	6-column	int	0	16
Column	37	Unused			blank
Columns	38-43	6-column	int	0	16
Column	44	Unused			blank
Columns	45-50	6-column	int	0	16
Column	51	Unused		-	blank
Columns	52-60	9-column	int	0	19

SP3 Lines Twenty seven to Thirty one (5 comment lines in example 1)

Columns	1-2	Symbols	/*	A2
Column	3	Unused	_	blank
Columns	4-80	Comment	cccc	A77

SP3 Line Thirty two (The Epoch Header Record)

Columns	1-2	Symbols	*	A2
Column	3	Unused	_	blank
Columns	4-7	Year Start	2013	I4
Column	8	Unused	_	blank
Columns	9-10	Month Start	_4	12
Column	11	Unused	_	blank
Columns	12-13	Day of Month St	_3	12
Column	14	Unused	_	blank
Columns	15-16	Hour Start	_0	12
Column	17	Unused	_	blank
Columns	18-19	Minute Start	_0	12
Column	20	Unused	_	blank
Columns	21-31	Second Start	_0.0000000	F11.8

SP3 Line Thirty three (The Position and Clock Record) (See example 1)

Column 1 Columns 2-4 Columns 5-18 Columns 19-32 Columns 33-46 Columns 47-60 Column 61 Columns 62-63 Column 64 Columns 65-66 Column 67 Columns 68-69 Column 70 Columns 71-73	Symbol Vehicle Id. x-coordinate(km) y-coordinate(km) z-coordinate(km) clock (microsec) Unused x-sdev (b**n mm) Unused y-sdev (b**n mm) Unused z-sdev (b**n mm) Unused c-sdev (b**n psec)	P G01 5783.206741 18133.044484 18510.756016 12.734450 	A1 A1,I2.2 F14.6 F14.6 F14.6 F14.6 blank I2 blank I2 blank I2 blank I2 blank I3
Columns 68-69 Column 70 Columns 71-73 Column 74 Column 75 Column 76	Z-Sdev (b**n mm) Unused C-sdev (b**n psec) Unused E=Clock Event Flag P=Clock Pred. Flag	 	l2 blank I3 blank A1 A1

 P_{age} **11**

Columns	77-78	Unused		2 blanks
Column	79	M=Maneuver Flag	_	A1
Column	80	P=Orbit Pred. Flag	_	A1

If the user wishes to include correlation information between the position components and the clock correction, then an optional Position and Clock Correlation Record can be added after each Position and Clock Record. This record gives the standard deviations for X, Y, Z, and clock correction with greater resolution than the approximate values given in the Position and Clock Record in columns 61 through 80.

SP3 Line Twenty five in Example 2. (The Position and Clock Correlation Record)

Columns Columns Columns Column	1-2 3-4 5-8 9	Symbols Unused x-sdev (mm) Unused	EP 55 55	A2 2 blanks I4 blank
Column	14	Unused		blank
Columns	15-18 19	z-sdev (mm)	55	I4 blank
Columns	20-26	clk-sdev (psec)	222	I7
Column Columns	27 28-35 36	unused xy-correlation		blank 18 blank
Columns	37-44 45	xz-correlation	-1234567	I8 hlank
Columns	46-53 54	xc-correlation	_5999999	I8 hlank
Columns	55-62	yz-correlation	30	I8 blank
Columns	64-71 72	yc-correlation	21	I8 blank
Columns	73-80	zc-correlation	-1230000	I8

The user can choose to include the optional Velocity and Clock Rate-of-Change Record, V, after each Position and Clock Record. The clock rate-ofchange units are 10**-4 microseconds/second for cols. 47-60 below.

SP3 Line Twenty six in Example 2.

Column 1 Columns 2- Columns 5- Columns 19 Columns 33 Columns 47 Column 61	-4 -18 3-32 3-46 7-60	Symbol Vehicle Id. x-velocity(dm/ y-velocity(dm/ z-velocity(dm/ clock rate-cho Unused yvel-sdev	/s) /s) /s)	V G01 20298.880364 18462.044804 1381.387685 4.534317 14	A1 F14.6 F14.6 F14.6 F14.6 F14.6 blank T2	. 2
	. 05	(b**n 10**-4 n	nm/sec	;)	12	
Column 64	1	Unused	,	_	blank	
Columns 65	5-66	yvel-sdev (b**n 10**-4 n	nm/sec	14	12	
Column 67	7	Unused	,	_	blank	
Columns 68	3-69	zvel-sdev (b**n 10**-4 n	nm/sec	14	12	
Column 70)	Unused	,	-	blank	

Columns	71-73	clkrate-sdev	191	13	3
		(b**n 10**-4	psec/sec)		
Columns	74-80	Unused		7	blanks

If the user wishes to include correlation information between the velocity components and the clock correction rate-of-change, then a separate Velocity and Clock Rate-of-Change Correlation Record can be added after each Velocity and Clock Rate-of-Change Record. This record gives the standard deviations for the X-, Y-, Z-velocities and the clock correction rate-of-change with greater resolution than the approximate values given in the Velocity and Clock Rate-of-Change Record.

SP3 Line Twenty seven in Example 2. - The Velocity and Clock Rate-of-Change Correlation Record.

Columns	1-2 3-4	Symbols	EV	A2 2 hlanks
Columns	5-8	xvel-sdev	22	I4
Column Columns	9 10-13	Unused yvel-sdev	22	blank I4
Column Columns	14 15-18	(10**-4 mm/sec) Unused zvel-sdev (10**-4 mm/sec)	22	blank 14
Column Columns	19 20-26	Unused clkrate-sdev (10**-4 psec/sec)	111	blank 17
Column Columns	27 28-35	Unused xy-correlation		blank I8 blank
Column Columns Column	36 37-44 45	vnused xz-correlation Unused	1234567	blank I8 blank
Columns Column	46-53 54	xc-correlation Unused	_1234567	18 blank
Columns Column	55-62 63	yz-correlation Unused	_1234567	18 blank
Columns Column	64-71 72	yc-correlation Unused	_1234567	18 blank
Columns	73-80	zc-correlation	_1234567	18

SP3 "Last" Line	(The End-of-File ma	irker)	
Columns 1-3	End of File	EOF	АЗ

If no Velocity and Clock Rate-of-Change Records or Correlation Records are present, and the number of satellites (NSAT) is less than or equal to 85, and the number of comment lines is equal to the minimally required 4, and the number of epochs = NEPCS, then the last line number in the file can be computed as:

Last Line number = 22+(NEPCS*(NSAT+1))+1.

If no Velocity and Clock Rate-of-Change Records or Correlation Records are

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present, and the number of satellites is greater than 85, and the number of comment lines (NCOMM) is greater than the required 4, then the last line # in the file can be computed (using the FORTRAN "INT" function) as follows:

Last Line number = 8+2*(INT(NSAT/17.01)+1)+NCOMM+(NEPCS*(NSAT+1))+1.

DETAILED DISCUSSION OF THE SP3-d FORMAT

Unless otherwise noted, the line numbers used below refer to Example 1. On line one, character two is the format version identification character. This fourth SP3 version has been designated version 'd'. Subsequent versions will use lower case letters in alphabetical order. The first line comprises the Gregorian date and time of day of the first epoch of the orbit, the number of epochs in the ephemeris file (up to 9,999,999), the data used descriptor, the coordinate system used descriptor, the orbit type descriptor, and the agency descriptor. The data used descriptor was included for ease in distinguishing between multiple orbital solutions from included for ease in distinguishing between multiple orbital solutions from a single organization. This will have primary use for the agency generating the orbit. A possible convention is given below; this is not considered final and suggestions are welcome.

- u -- undifferenced carrier phase
- du -- change in u with time
 s -- 2-receiver/1-satellite carrier phase
- ds
- -- change on s with time -- 2-receiver/2-satellite carrier phase d
- dd -- change in d with time U -- undifferenced code phase
- dU -- change in U with time
- -- 2-receiver/1-satellite code phase S
- -- change in S with time dS
- -- 2-receiver/2-satellite code phase D
- dD -- change in D with time
- + -- type separator

Combinations such as "__u+U" seem reasonable. If the measurements used were complex combinations of standard types, then one could use "mixed' where mixed could be explained on the comment lines. In example 1, the file is a combination of orbits from several agencies and so the data used is designated as 'ORBIT'.

The Coordinate System or Reference Frame in which the satellite positions and velocities are given is described by a five character code. In the early years of the IGS, codes such as IER91, IER92, IER93, ITR94, etc. were used. More recent years have used IGS05, IGS08, and IGb08 - which are IGS realizations of the ITRF2005 & ITRF2008 reference frames, respectively. The reference frame "WGS84" is used in Example 1 to stress the fact that the satellite positions are derived from a set of broadcast ephemerides from the various GNSS constellations. In this case, the reference frames used by the GNSS may be different at the centimeter level, but the accuracy of the orbit information itself is at the meter level -- and at that level the frames can be considered coincident.

Orbit type is described by a three character descriptor. At this time only four have been defined: FIT (fitted), EXT (extrapolated or predicted), BCT (broadcast), and HLM (fitted after applying a Helmert transformation). Naturally, others are possible. The computing agency descriptor allows four characters (e.g. _NGS, _IGS, MGEX, etc.).

The second line has: the GPS week; the seconds of the GPS week elapsed at the start of the orbit (0.0 <= seconds of week < 604800.0); the epoch interval (0.0 <epoch interval < 100000.0) in seconds; the modified Julian

Day Start (where 44244 represents GPS zero time -- January 6, 1980); and fractional part of the day (0.0 <= fractional < 1.0) at the start of the orbit.

The third line to the eleventh line (in Example 1) indicates the number of satellites followed by their respective identifiers. For the SP3-d format, the maximum number of satellites has been increased from 85 to 999. Hence there can now actually be more than five "+ " lines if there are more than 85 satellites. For the sake of backwards compatibility, if an SP3-d file has less than 85 satellites, it must still have five satellite ID ("+ ") lines. The identifiers must use consecutive slots and continue on as many lines as required. The value 0 should only appear after all the identifiers are listed (see Example 1). Satellite identifiers may be listed in any order. However, for ease in reviewing satellites included in the orbit file it is recommended that numerical order be used. Each identifier will consist of a letter followed by a 2-digit integer between 01 and 99. For example, "Gnn" for GPS satellites, "Rnn" for GLONASS satellites, "Lnn" for Low-Earth Orbiting (LEO) satellites, "Enn" for Galileo satellites, "Cnn" for BeiDou Navigation Satellite System (IRNSS) satellites, and "Jnn" for the Japanese Quasi-Zenith Satellite System (QZSS) satellites. For QZSS the nn=PRN-192 rule is applied, for example QZS-1 (PRN=193) is expressed by "JO1". Other letters will be allowed for other types of satellites. Lower numbered satellites must always have a preceding zero (e.g., "G09" not "G 9"). The letter, which represents the Satellite System Indicator, must always be present (i.e.," 09" is no longer a valid satellite identifier). This is a significant change from SP3-a and needs to be noted when software is updated to read the new SP3-c or SP3-d format. A list of identifiers created for LEO satellites can be viewed at http://cddis.gsfc.nasa.gov/Sp3c_satlist.html . A list of identifiers for the SBAS satellites can be viewed at: http://cddis.gsfc.nasa.gov/Sp3c_satlist.html . A list of identifiers for the

The twelfth to the twentieth lines hold the orbit accuracy exponents. The value 0 is interpreted as accuracy unknown. A satellite's accuracy exponent appears in the same columns within these lines as the identifier on the satellite ID lines. The accuracy is computed from the exponent as in the following example. If the accuracy exponent is 13, the accuracy is 2**13 mm or ~ 8 m. The quoted orbital error should represent one standard deviation and be based on the orbital error in the entire file for the respective satellite. This may lead to some distortion when orbit files are joined together, or when a file contains both observed and predicted data.

On the twenty-first line, columns 4-5 hold the File Type descriptor. This is a single character left-justified in the two-character field. The currently defined values are: "G " for GPS only files, "M " for mixed files, "R " for GLONASS only files, "L " for LEO only files, "S " for SBAS only files, "I " for IRNSS only files, "E " for Galileo only files, "C " for BeiDou only files, and "J " for QZSS only files. No default values are implied; either "G ", "M ", "R ", "L ", "S ", "I ", "E ", "C ", or "J " is required. On this same line, columns 10-12 hold the Time System Indicator. In order to remove any ambiguity with respect to which time system is being used in mixed files, this field specifies the time system used in each SP3-d file: use "GPS" to identify GPS Time, "GLO" to identify the GLONASS UTC time system, "GAL" to identify Galileo system time, "BDT" to identify BeiDou system time, "TAI" to identify International Atomic Time, "UTC" to identify Coordinated Universal Time, "IRN" to identify IRNSS Time, or "QZS" to identify QZSS Time. No default value is implied; either "GPS", "GLO", "GAL", "BDT", "TAI", "UTC", "IRN", or "QZS" must be specified.

On Line twenty-three, columns 4-13 would hold the floating-point base number used for computing the standard deviations for the components of the satellite position and velocity. Instead of using 2**nn as is done in the orbit accuracy lines 12-20 in the header, better resolution can be attained

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using a number like 1.25**nn. The units for position and velocity are mm and 10**-4 mm/sec, respectively. Likewise, columns 15-26 would hold the floating-point base number for computing the standard deviations for the clock correction and the rate-of-change of the clock correction. Again, instead of using 2**nnn, one might use a number like 1.025**nnn (see also Example 2). The units for the clock correction and the rate-of-change of the clock correctively.

Lines 21-26 (the six lines that begin with the character "%") have been designed so that additional parameters may be added to the SP3 format.

Lines 27-31 in Example 1 are free form comments (comments go in columns 4-80). For backwards compatibility, there will always be at least 4 comment lines. These can be filled with "/* CCCCC...CCC" or with "/* ". The comment lines should be read in until the first Epoch Header Record (i.e. the first time tag line) is encountered.

Line 32 is the first Epoch Header Record, showing the epoch date/time.

Line 33 is the first Position and Clock Record; the first character is always 'P'. The positional values are in kilometers and are precise to 1 mm. A precision of 0.5 mm can be accommodated if rounding is used, i.e., the value shown is never more than 0.5 mm from the computed value. The clock values are in microseconds and are precise to 1 picosecond. Bad or absent positional values are to be set to 0.000000. Bad or absent clock values are to be set to _999999.999999. The six integer nines are required, whereas the fractional part nines are optional.

On Line 24 in Example 2. Columns 62-69 hold the two digit exponents which represent the standard deviations of the satellite coordinates in units of millimeters. For example, if the base floating point number from line fifteen is 1.25, and the two-digit exponent for the X-coordinate is 18, then the standard deviation of the X-coordinate is 1.25**18 = 55.5112 or approximately 56 mm. In a similar manner, columns 71-73 hold a three-digit exponent representing the standard deviation for the clock correction in units of picoseconds. As an example, if the base floating point number from line fifteen is 1.025, and the three-digit exponent for the clock correction is 219, then the standard deviation of the Clock correction is 1.025**219 = 223.1138 or approximately 223 picoseconds. An exponent value of 99 or 999 would mean that a standard deviation was too large to represent. If a standard deviation is unknown, its field is left blank. Column 75 is the Clock Event Flag (either 'E' or blank). An 'E' flag is used to denote a discontinuity in the satellite clock correction (this might be caused by a clock swap on the satellite. The discontinuity is understood to have occurred sometime between the previous epoch and current epoch, or at the current epoch. A blank means either no event occurred, or it is unknown whether any event occurred. Column 76 is the Clock Correction rediction Flag (either 'P' or blank). A 'P' flag indicates that the satellite clock correction is observed. Column 79 is the orbit Maneuver Flag (either 'M' or blank). A 'P' flag indicates that the clock correction so beserved. Column 79 is the orbit Maneuver Flag (either 'M' or blank). An 'M' flag indicates that sometime between the previous epoch and the current epoch, or at the current epoch, or at the current epoch, or at the current epoch. A blank means that the satellite. As an example, if a certain maneuver took place for this satellite. As an example, if a certain maneuver lasted 50 minutes (a satellite. As an example, if a certain maneuver lasted

missing columns should be interpreted as blanks. Any program reading an SP3-d file must be prepared to deal with short records (either by padding with blanks, or by some other method).

Line 25 (in example 2) is the optional Position and Clock Correlation Record. This record type always begins with the characters 'EP'. Columns 5-18 give the standard deviations for the X,Y,Z satellite coordinates in units of mm. The standard deviations in this record are given to greater resolution than the approximate values given in the Position and Clock Record. A value of 9999 would mean that a standard deviation was too large to be represented. If a standard deviation is unknown, its field is left blank. Columns 20-26 give the standard deviation of the clock correction in units of picoseconds. A value of 9999999 would mean that the standard deviation was too large to be represented. Columns 28-80 are used to store the correlation coefficients for xy, xz, xc, yz, yc, and zc. Each 8-digit integer would be divided by 10,000,000 to produce a correlation coefficients are omitted, a Position and Clock Correlation Record may contain less than 80 columns.

Line 26 (in example 2) is the optional Velocity and Clock Rate-of-Change Record. This type of record always begins with the character 'V'. When the position/velocity mode flag is set to 'V' in line one, then each Position and Clock Record for a satellite will be followed by a corresponding Velocity and Clock Rate-of-Change Record (although in some cases there may be a Position and Clock Correlation Record in between the two). The satellite velocity components are given in columns 5-46 in units of decimeters/second and have a precision of 10**-4 millimeters/second. Columns 47-60 give the rate-of-change of the clock correction in units of 10**-4 microseconds/second. The precision of this parameter is 10**-16 seconds/second. Bad or absent velocity values are to be set to 0.000000. Bad or absent clock rate-of-change values are to be set to _999999.99999. The six integer nines are required, whereas the fractional part nines are optional. In a manner similar to the Position and Clock Record, columns 62-69 hold two-digit exponents for representing the standard deviation of the X-, Y-, Z-velocities (e.g., 1.25**14 = 22.7374 or approximately 0.0022 mm/sec). Columns 71-73 hold a three-digit exponent for representing the standard deviation of the clock correction rate-of-change (e.g., 1.025**191 = 111.7528 or approximately 0.0112 psec/sec). A value of 99 or 999 would mean that a standard deviation was too large to represent. If a standard deviation is unknown, its field is left blank. If one or more fields in columns 61 through 73 are omitted, a Velocity and Clock Rate-of-Change Record may contain less than 73 columns.

Line 27 (in example 2) is the optional Velocity and Clock Rate-of-Change Correlation Record. This type of line always begins with the characters 'EV'. Columns 5-18 give the standard deviations for the X-, Y-, Z-velocities in units of 10**-4 millimeters/second. The standard deviations of the velocity components are given to greater resolution than the approximate values given in the Velocity and Clock Rate-of-Change Record. A value of 9999 would mean that a velocity standard deviation was too large to be represented. Columns 20-26 give the standard deviation of the clock correction rate-of-change in units of 10**-4 psec/sec. A value of 9999999 would mean that the clock correction rate-of-change was too large to be represented. If a standard deviation is unknown, its field is left blank. Columns 28-80 are used to store the correlation coefficients between the velocity components and the clock correction rate-of-change (xy, xz, xc, yz, yc, and zc). Each 8-digit integer would be divided by 10,000,000 to produce a correlation coefficients between -0.9999999 and +0.9999999. If some of the correlation coefficients are omitted, a Velocity and Clock Rate-of-Change Correlation Record may contain less than 80 columns.

FINAL NOTE: Any software which reads SP3-d files must be prepared to read the 'EP' and 'EV' correlation records if they are present. If the person or agency reading the file decides that the correlation information (and the more accurate standard deviations) are not needed, then these 'EP' and 'EV' records might be simply ignored and skipped over. There may be only a few EP and/or EV records placed in an SP3-d file, i.e., it is not necessary to have EP and/or EV records for every satellite at every epoch. The only rule is: since no satellite IDs are given in the optional EP and EV records, they must immediately follow their corresponding P or V record for that satellite. The satellite order of the P, EP, V, and EV records (or subset of these) must be the same as the order of the satellite ID records (those beginning with "+ ") in the header. Thus the order and the total number of satellites at each epoch must always be the same. This serves as an integrity check on the file -- i.e., satellites must be designated as "bad" or "absent" by intentionally setting their position (and velocity) values equal to zero. There should never be any satellite's Position or Velocity records left out at an epoch. Since not all SP3-d records will contain their maximum number of columns, missing columns should be interpreted as blanks. Any program reading an SP3-d file must be prepared to deal with short records (either by padding with blanks, or by some other method).

ACKNOWLEDGMENTS

The idea for using floating-point base numbers (1.25**nn and 1.025**nnn, rather than 2**nn) to improve the resolution of the standard deviations was suggested by Benjamin Remondi. Most of the extensions added to the later versions of the SP3 format have been relatively minor; it is a testament to Dr. Remondi's foresight and ingenuity that the SP3 format has been used now for over twenty years. The author would also like to thank the several members of the IGS community who offered comments and suggestions on the design of the SP3-c and SP3-d formats so far: Henno Boomkamp, Kevin Choi, Oscar Colombo, Rolf Dach, Gerd Gendt, Jake Griffiths, Werner Gurtner, Urs Hugentobler, Jan Kouba, Sylvain Loyer, Stephen Malys, Oliver Montenbruck, Tomas Martin Mur, Jim Ray, Ignacio Romero, Markus Rothacher, Mark Schenewerk, Victor Slabinski, Tim Springer, Everett Swift, and Robert Weber.

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APPENDIX A - The History of the SP3 Format

The original Standard Product 3 format (SP3-a) was first proposed by Benjamin Remondi in (Remondi, 1989) and modified and adopted in (Remondi, 1991). The SP3 format is similar to the original NGS Standard Product 1 format described in (Remondi, 1989 and 1985) but includes additional information: satellite clock corrections, orbit accuracy exponents, comment lines, the GPS week and seconds of week associated with the first epoch, and a more flexible header structure (Spofford and Remondi, 1994).

In 1998, W. Gurtner and M. Rothacher defined an SP3-b format to allow for the combination of GPS orbits and GLONASS orbits (see IGEX Mail 0042, 27-Oct-1998). All of these SP3-b modifications were backwards compatible with SP3-a, with the exception of the satellite identification labels – which were changed from an I3 field to an A1,I2 field to accommodate both GPS and GLONASS identifiers in a manner similar to RINEX files (Gurtner, 2000).

At the 2000 International GPS Service (IGS) Analysis Center Workshop held at the U.S. Naval Observatory, it was suggested to modify the SP3 format still further so that orbit files distributed by the IGS could include some type of clock accuracy information, and so that separate accuracy information would be available for the observed versus predicted parts of the IGS ultrarapid orbit files. Rather than just putting two sets of accuracy exponents in the header (one for the observed part and one for the predicted part) it was decided instead to put accuracy information at each epoch (for X, Y, Z, and satellite clock correction). Since the original SP3-a and SP3-b formats were only 60 columns wide, this additional information was easily added using columns 61 through 80 in each Position and Clock Record. This was done in such a way as to remain mostly backwards compatible with SP3-a. As comments were collected from the IGS (orbit) Analysis Centers, additional ideas emerged. It was suggested that a clock event flag be added in column 75 (as currently done by some groups) to denote events like a clock swap on a satellite. It was also suggested to add an orbit event flag, to denote cases where it was known that a satellite went through some type of orbit maneuver. It was also suggested that clock prediction and orbit prediction flags be added. Finally, for the purposes of computing user range errors more accurately for each satellite, it was suggested to add correlation information between the satellite coordinates and the satellite clock correction. These ideas were discussed further at the 2002 IGS Network, Data, and Analysis Center Workshop held in Ottawa (Hilla, 2002).

All of these suggestions were incorporated in the SP3-c format. As a result, there can now be as many as three different sets of satellite position accuracy indicators in any SP3-c or SP3-d file. The first set, the original accuracy exponents in the header, have been kept in SP3-d to maintain backwards compatibility with the SP3-a format and with existing GPS processing software. These exponents are interpreted as 2**nn millimeters. A zero exponent means the accuracy is unknown. The quoted orbit error should represent one standard deviation and be based on the orbital error in the entire file for the respective satellite. The second set, in columns 62 through 69 of the Position and Clock Record, represent the standard deviation of each position component (X, Y, and Z) at that epoch, in millimeters. These are also exponents but use a floating-point base (for example, 1.25**nn) to achieve better resolution for the standard deviations. A zero exponent here represents a 1 millimeter standard deviation. Blank spaces mean the standard deviation is unknown. These first two sets of standard deviations are currently present in all IGS-produced SP3-c files.

A third set of standard deviations can be found in the optional Position and Clock Correlation Record (the EP record). This optional record was added to provide high precision users with the correlation coefficients between the X, Y, Z, and satellite clock correction values. In order to be able to construct the full 4-by-4 covariance matrix for a satellite at an epoch, without any loss of precision, the standard deviations for the X, Y, and Z position components are given here to full millimeter precision using a range of 1 to 9999 millimeters. Blank spaces mean a standard deviation or a correlation coefficient is unknown (blanks would probably only occur for the clock information, unless the EP records were being used to store only standard deviations, or only correlation coefficients).

In this document the format fields for the SP3-d format are defined. These include all of the changes made for SP3-c. The fields that are defined as "blanks" are reserved fields which must remain blank. All times referred to in an SP3-d file are in the SAME time system, even when they are represented as Gregorian Dates or Modified Julian Dates. In SP3-d, the Time System code for the entire file (GPS, GLO, GAL, BDT, TAI, QZS, or UTC) is now specified in the header on line thirteen. The information to convert between GPS Time and Coordinated Universal Time (i.e., the leap seconds and the fractional error in GPS Time) is not provided as part of the SP3 format. The basic format of an SP3 file is a Header, followed by a series of epoch times each with a set of Position and Clock Records listed for each satellite. A second, optional record contains satellite velocities and the clock correction rate-of-change. The Position Record Flag, P, in line one, column 3, indicates that at each epoch, for each satellite, an additional satellite velocity and clock rate-of-change has been computed. SP3-c added two more optional records: a Position and Clock Correlation Record (EP record), and a Velocity and Clock Rate-of-Change Correlation Record (EV record).

APPENDIX B - Modification History of the SP3-c and SP3-d Formats

Note: The original SP3-c format document was dated 5 September 2002.

Note: The IGS began using the SP3-c format for Rapid and Ultra Rapid Products from GPS week 1285.1, and for Final Products from week 1283. See IGSMAIL-5000 sent by Gerd Gendt on 27 August 2004. The new files had the extension ".sp3c". For a time, both the SP3-a and the SP3-c files were made available.

Note: Beginning on 29 January 2006, the IGS made their precise ephemeris files available only in the new SP3-c format.

Note: On 27 September 2006, the sp3c.txt file was updated slightly to add more options for the Time System Indicator. The original version had only "GPS" and "UTC" as options for the Time System Indicator. This new version adds codes "GLO", "GAL", and "TAI". Also, clarifications were made regarding the EP and EV records, and the order of the satellites and records at each epoch.

Note: On 12 February 2007, the sp3c.txt file was modified to include a reference to a new list of LEO satellites available at CDDIS (see the documentation below regarding the satellite identifiers found in the third through seventh lines).

Note: On 17 August 2010, the sp3c.txt file was modified to add satellite system identifiers for J = QZSS and C = COMPASS, and to add "QZS" as a Time System indicator for QZSS Time.

Note: On 8 August 2013, the first draft version of SP3-d was written. This version increases the maximum number of satellites from 85 to 999, allows for unlimited comment records, and increases the length of the comment records from 60 characters to 80 characters. Additional Satellite ID letters were added for Satellite-Based Augmentation System (SBAS) satellites, and for the Indian Regional Navigation Satellite System (IRNSS) satellites: "S" and "I", respectively.

Note: On 17 September 2013, BeiDou system time (BDT) was added and all references to "COMPASS" were deleted.

Note: On 15 January 2016, IRNSS system time (IRN) was added, several URL links were updated, and a few clarifying statements were added. [This third draft version of SP3-d was then sent to the IGS Analysis Centers for comments].

Note: On 21 February 2016, following the adoption of SP3-d by the Multi-GNSS Working Group at the 2016 IGS Workshop in Sydney, Australia, minor grammatical corrections were made, and the word DRAFT was removed from the title.