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GNSS Tracking Issues

Stefan C. Schaer

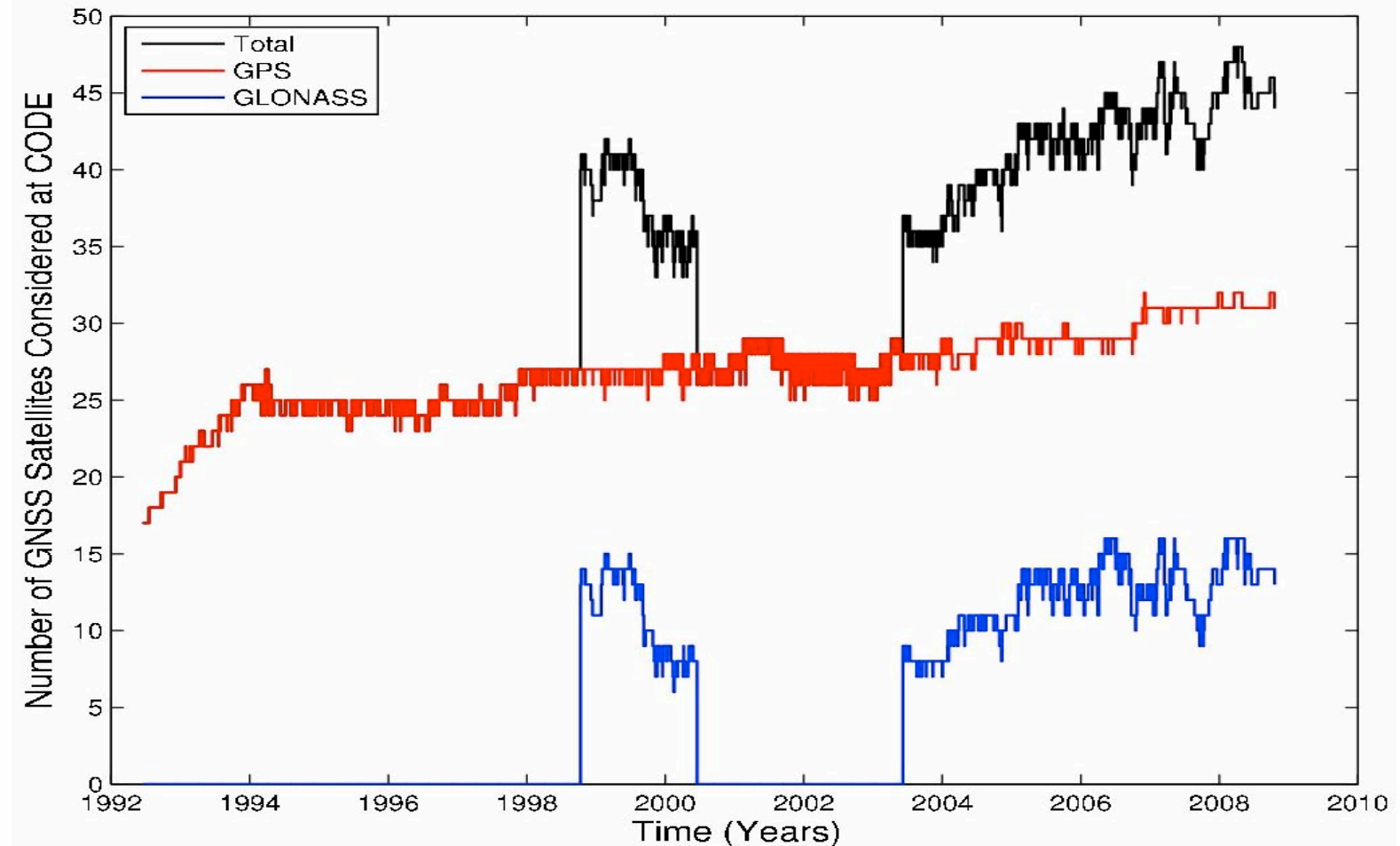


Outline

- Current GNSS satellite constellation
- GLONASS negative frequency channels
- Improved IGS GNSS receiver coverage
- Survey of employed IGS GNSS receiver and antenna/radome models
- Quarter-cycle issue (RINEX/RTCM)

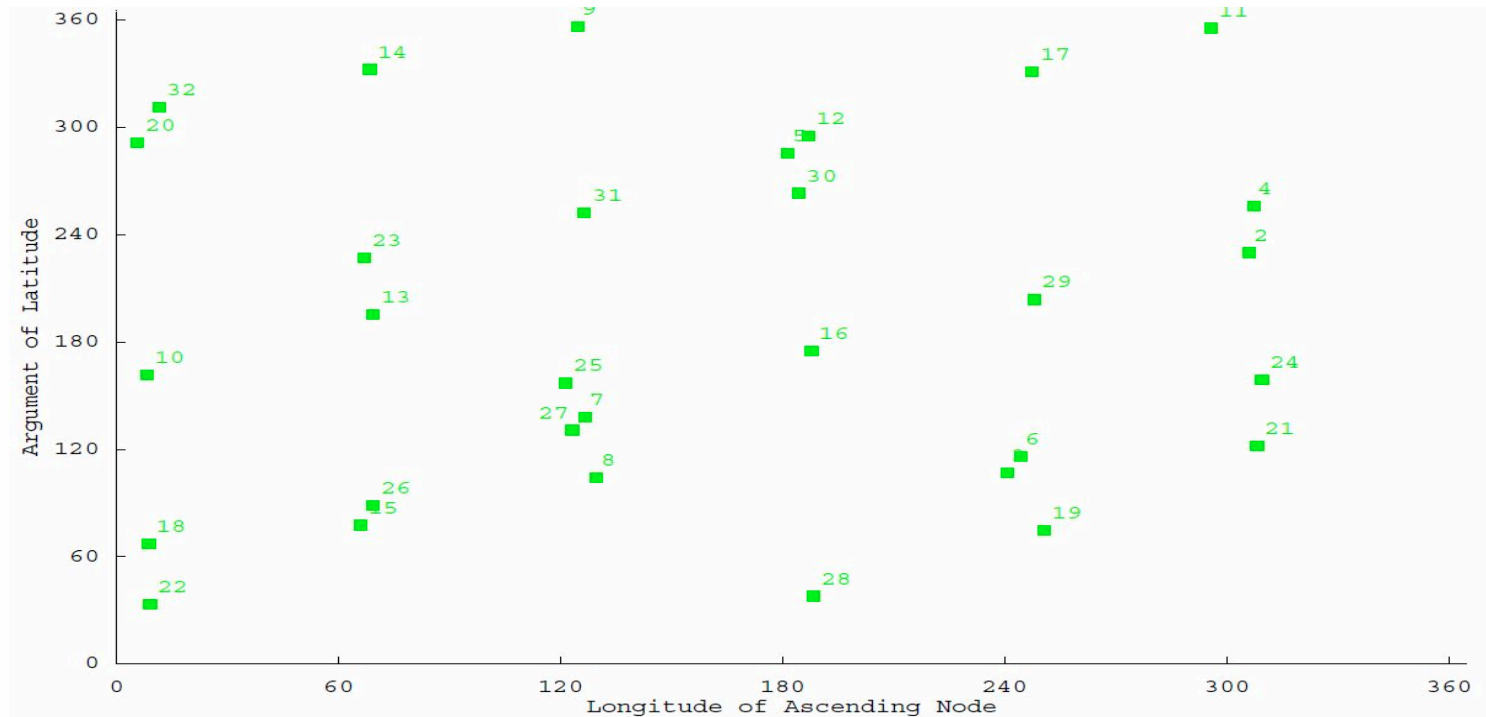


GNSS Satellite Constellation





GPS Constellation: 31 Satellites



<http://gge.unb.ca/Resources/GPSConstellationPlot.pdf>



GPS PRN32 Tracking (1/2)

ftp://ftp.unibe.ch/aiub/igsdata/tracking_prn32_sum.txt:

```
AOA BENCHMARK ACT : 100% ( 19 of 19)
AOA SNR-12 ACT : 100% ( 3 of 3)
AOA SNR-8000 ACT : 100% ( 4 of 4)
AOA SNR-8100 ACT : 100% ( 1 of 1)
ASHTECH UZ-12 : 100% ( 51 of 51)
ASHTECH Z-X : 100% ( 1 of 1)
ASHTECH Z-XII3 : 100% ( 56 of 56)
ASHTECH Z-XII3T : 100% ( 14 of 14)
ASHTECH Z18 : 50% ( 2 of 4)
BLACKJACK : 100% ( 2 of 2)
JPS EGGDT : 100% ( 5 of 5)
JPS EUROCARD : 100% ( 1 of 1)
JPS E_GGD : 100% ( 7 of 7)
JPS LEGACY : 100% ( 22 of 22)
LEICA CRS1000 : 100% ( 2 of 2)
LEICA GRX1200 : 100% ( 2 of 2)
LEICA GRX1200GGPRO : 100% ( 32 of 32)
LEICA GRX1200PRO : 100% ( 3 of 3)
LEICA RS500 : 100% ( 1 of 1)
NOV EURO4-1.00-222 : 100% ( 1 of 1)
NOV OEMV3 : 100% ( 2 of 2)
ROGUE SNR-8000 : 100% ( 5 of 5)
SEPT POLARX2 : 100% ( 6 of 6)
TPS EGGDT : 100% ( 1 of 1)
TPS EUROCARD : 100% ( 1 of 1)
TPS E_GGD : 100% ( 12 of 12)
TPS GB-1000 : 100% ( 4 of 4)
TPS LEGACY : 100% ( 3 of 3)
TPS NET-G3 : 100% ( 1 of 1)
TPS NETG3 : 100% ( 4 of 4)
TPS ODYSSEY_E : 100% ( 4 of 4)
TRIMBLE 4000SSE : 100% ( 2 of 2)
TRIMBLE 4000SSI : 100% ( 9 of 9)
TRIMBLE 4700 : 100% ( 2 of 2)
TRIMBLE 5700 : 100% ( 2 of 2)
TRIMBLE NETR5 : 100% ( 22 of 22)
TRIMBLE NETRS : 80% ( 17 of 21)
-----
TOTAL : 98% (326 of 332)
```



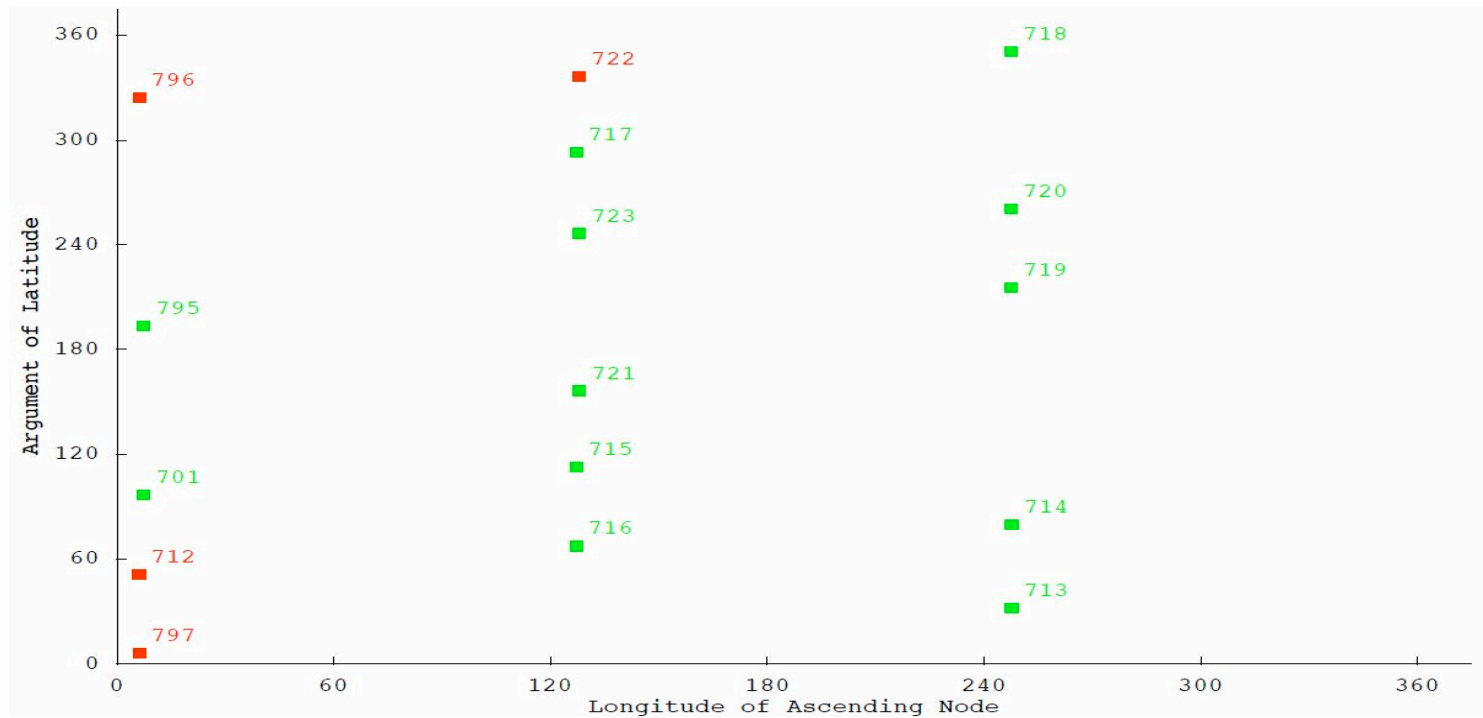
GPS PRN32 Tracking (2/2)

ftp://ftp.unibe.ch/aiub/igsdata/tracking_prn32_not_ready.txt:

ASHTECH Z18	0065	:	gope
ASHTECH Z18	0065 ZT16	:	mtka
TRIMBLE NETRS	0.4-1 G27 OCT 2005	:	pgc5
TRIMBLE NETRS	1.1-5	:	amu2
TRIMBLE NETRS	NP 1.13 / SP 0.00	:	ssia
TRIMBLE NETRS	NP 1.15 / SP 0.00	:	kgni



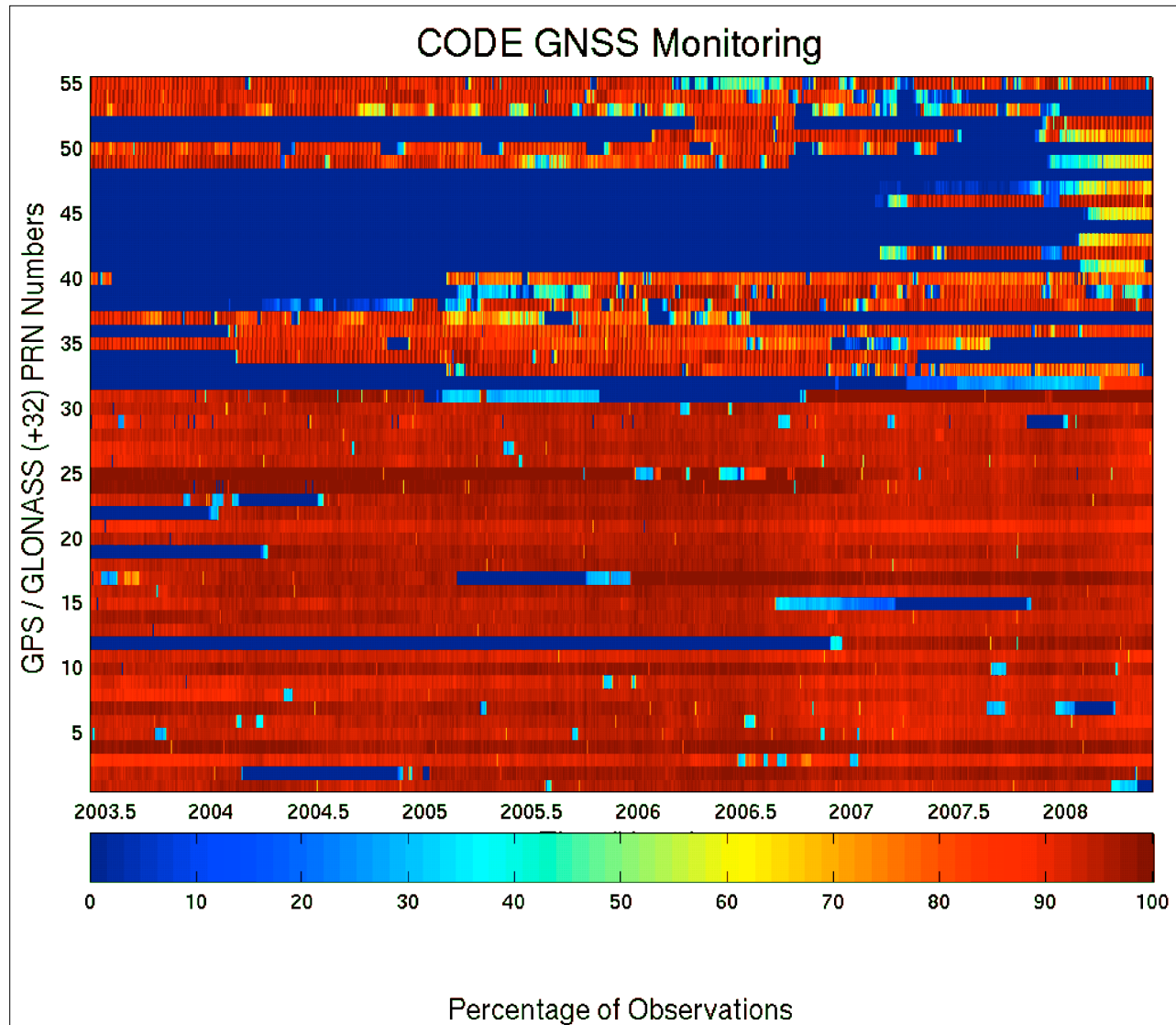
GLONASS Constellation: 13+3(+1)



<http://gge.unb.ca/Resources/GLONASSConstellationPlot.pdf>

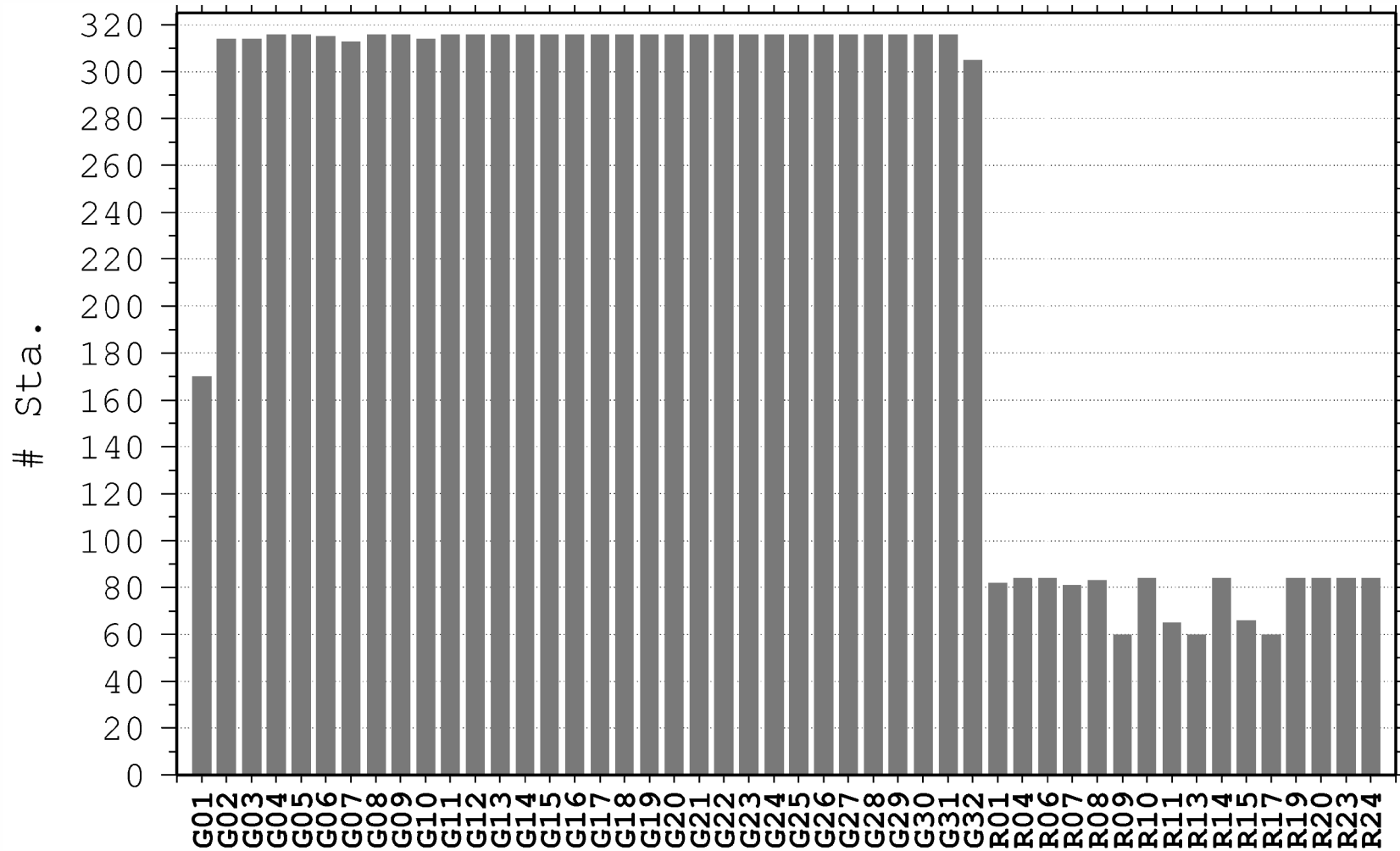


CODE GNSS Monitoring



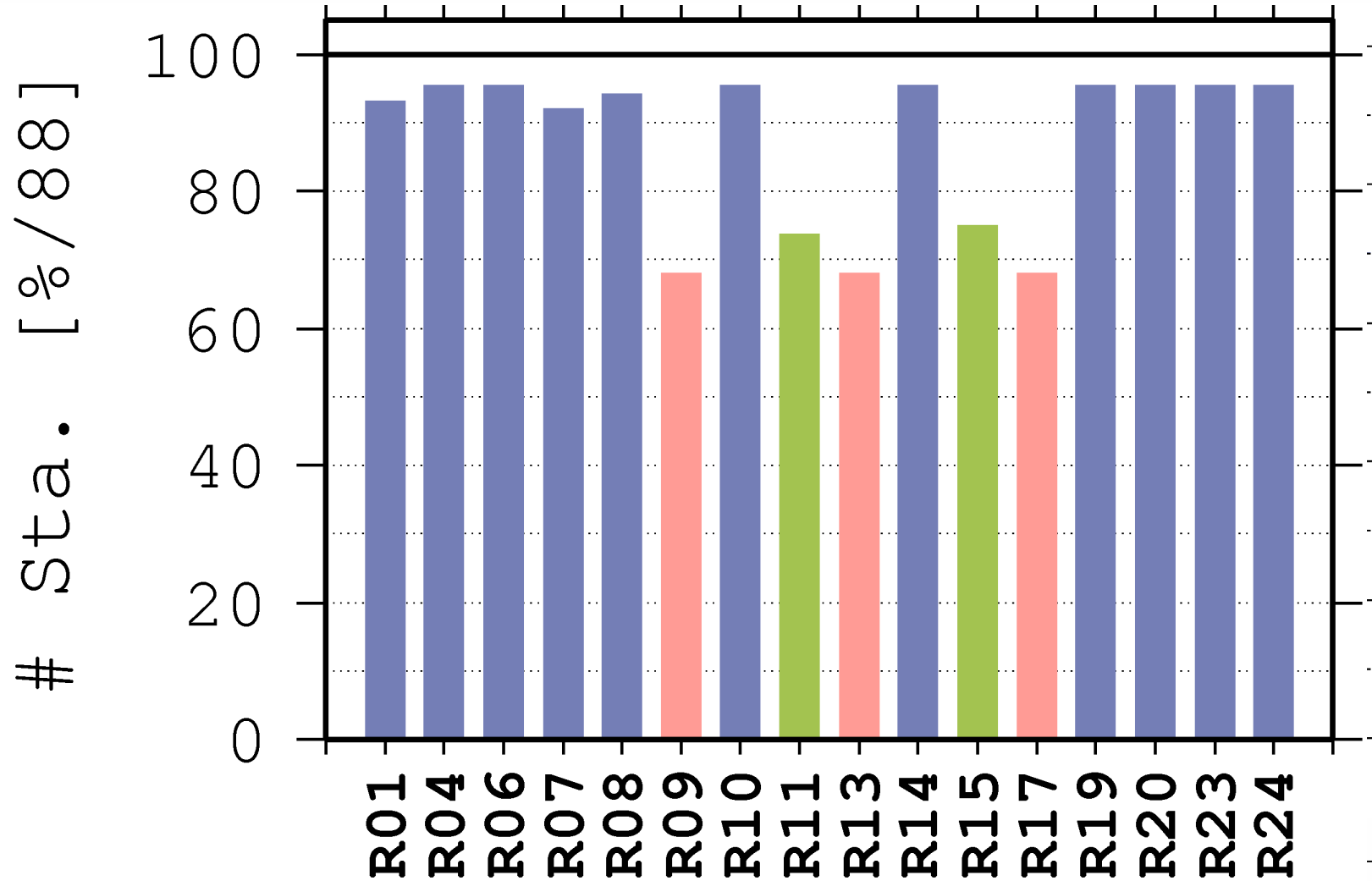


Number of GNSS Stations Tracking a Specific GPS/GLONASS Satellite (for April 2008)





Number of GNSS Stations Tracking a Specific GPS/GLONASS Satellite (for April 2008)





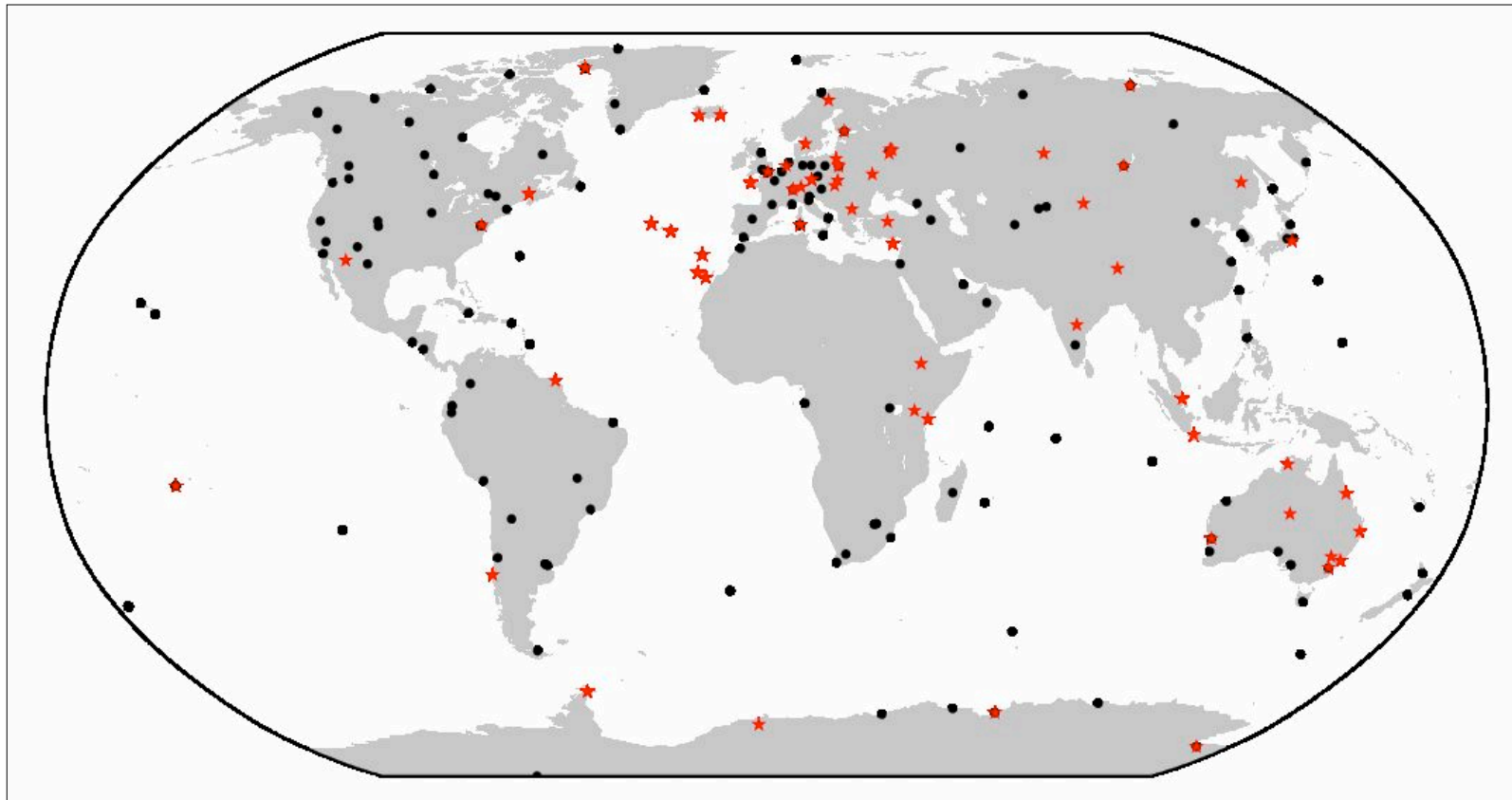
GLONASS Negative Frequency Channels

ftp://ftp.unibe.ch/aiub/igsdata/tracking_glo_neg_freq_not_ready.txt

bako:	R11	R15	LEICA GRX1200GGPRO	5.00/3.013	
cagz:			TPS E_GGD	3.1	MAR,13,2007 P2
crar:			TPS ODYSSEY_E	2.5	JUN,22,2005 P1
ctwn:	R11	R13	R15	R17	TRIMBLE NETR5 N/A
ilha:	R11	R15	LEICA GRX1200GGPRO	5.10	
mobj:			TPS LEGACY	2.3	APR,28,2004 P4
mtbg:	R11	R15	TPS GB-1000		
mtka:			ASHTECH Z18	0065	ZT16
park:			JPS E_GGD	2.5	
pous:			TPS GB-1000	2.5	APR,07,2005 P1B1
snec:			TPS GB-1000	2.5	JUN,22,2005 P1
sydn:			JPS E_GGD	2.3	P3
tixj:			TPS ODYSSEY_E	2.5	JUN,22,2005 P1
tsea:	R11	R15	LEICA GRX1200GGPRO	4.10	
unpg:			TPS ODYSSEY_E	3.1	JUN,28,2007 P3
ven1:			ASHTECH Z18	0065	ZT16
vesl:		R13	TPS GB-1000	3.1	JUN,28,2007 P3



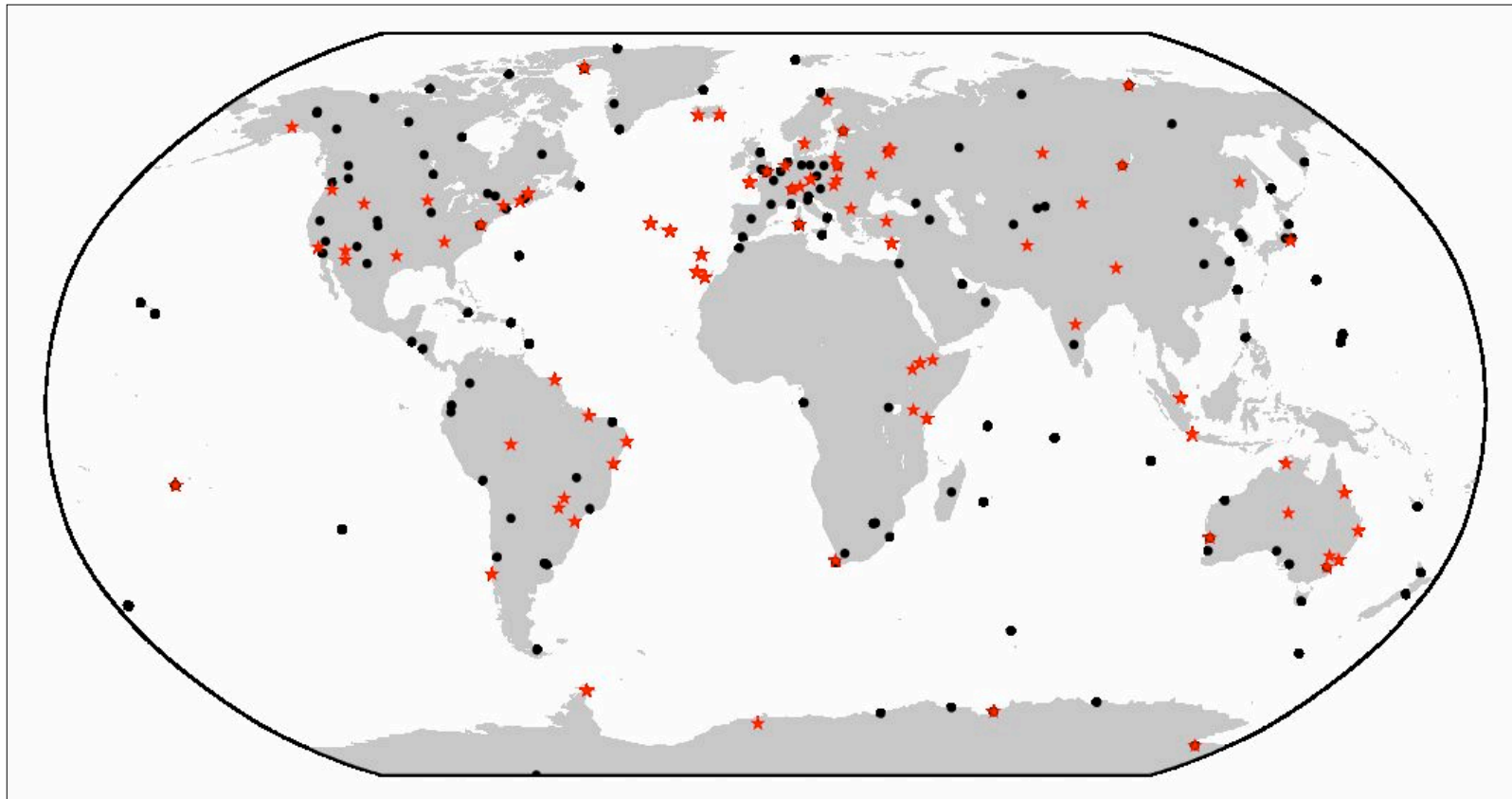
GNSS Receiver Network as Used in CODE's Final Analysis (for GPS Weeks 1497-1498)



227 GNSS stations: 158 GPS-only (70%) + 69 GPS/GLONASS (30%)



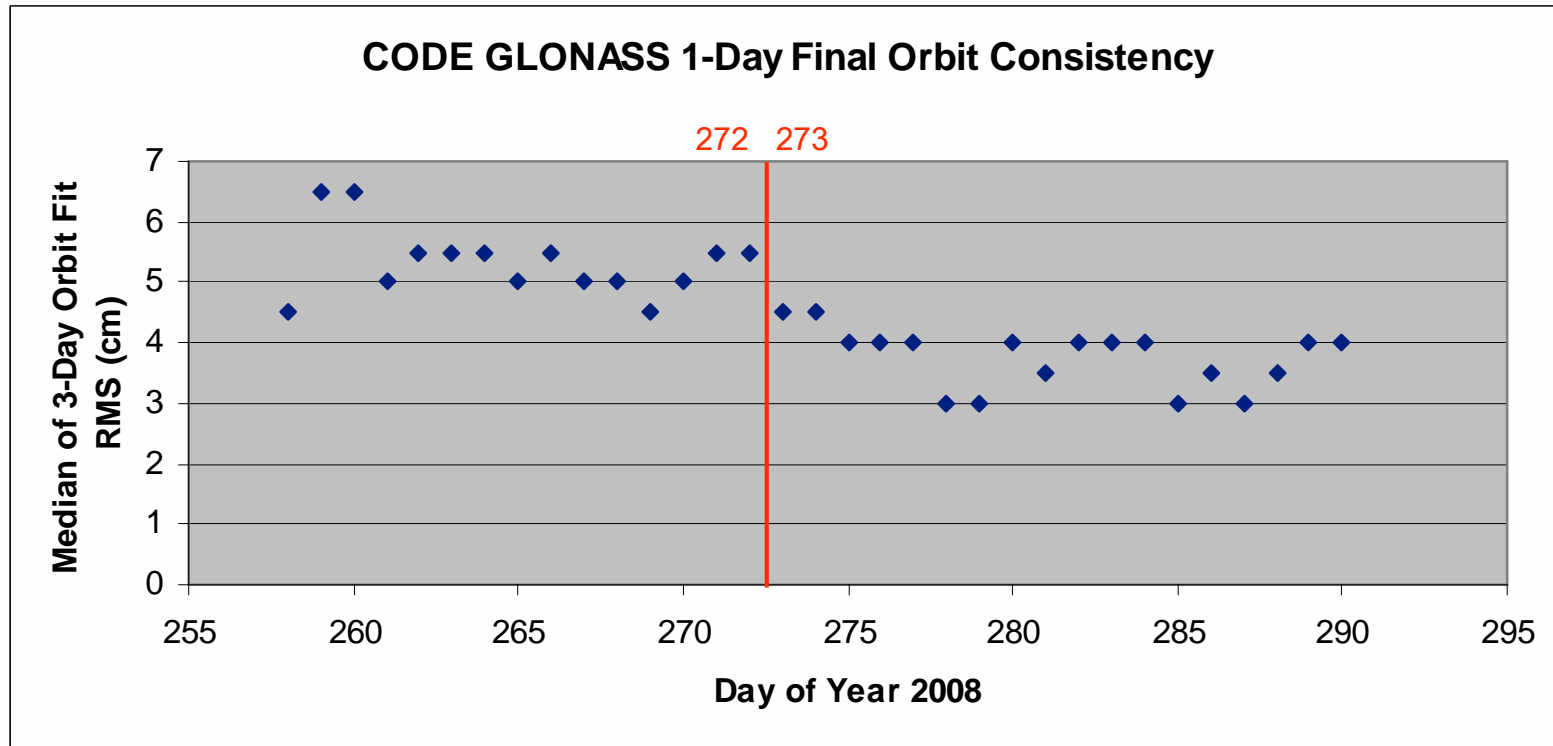
GNSS Receiver Network as Used in CODE's Final Analysis (for GPS Weeks 1499-1500)



250 GNSS stations: 160 GPS-only (64%) + 90 GPS/GLONASS (36%)

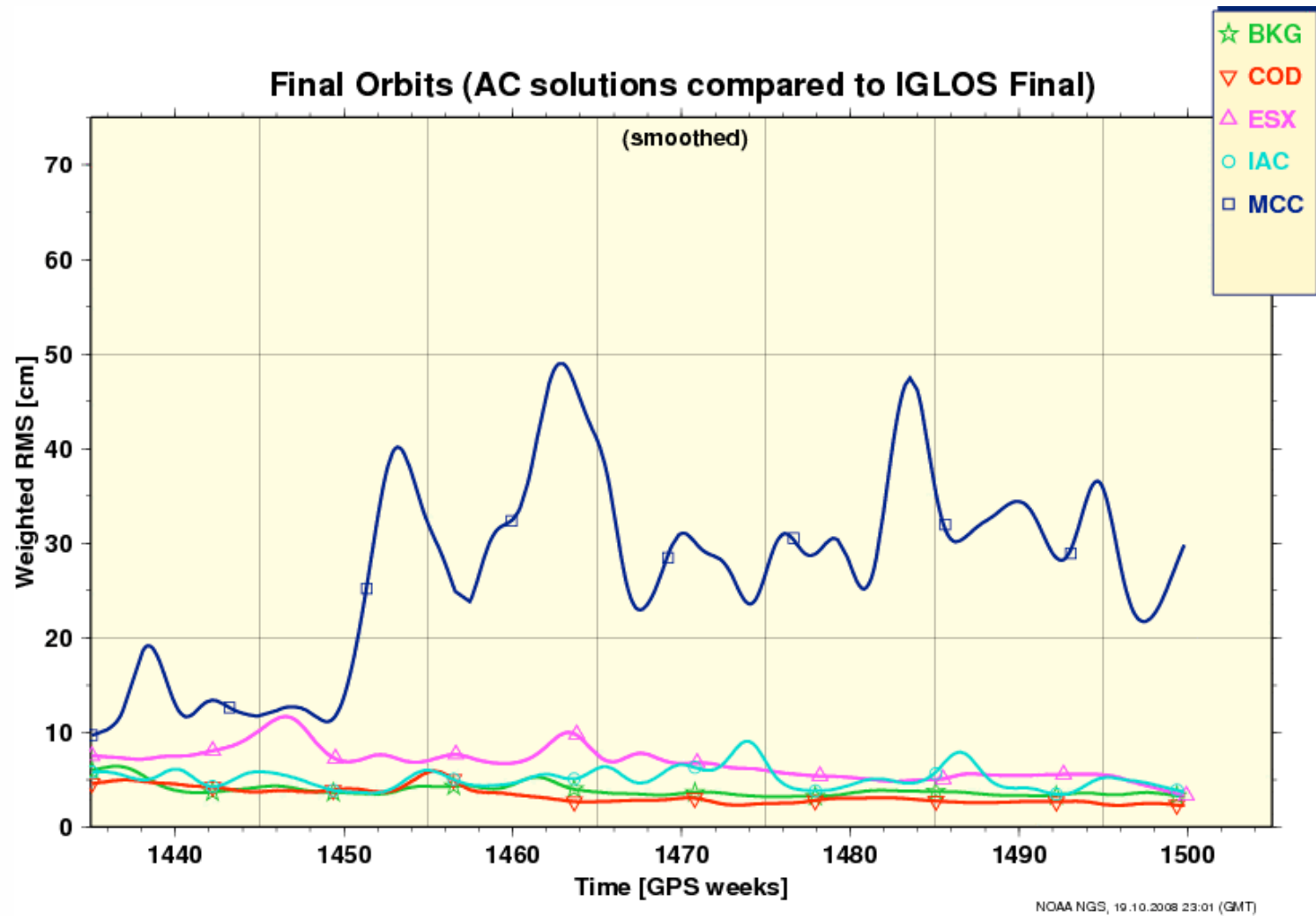


Validation of CODE's GLONASS 1-Day Final Orbit Consistency





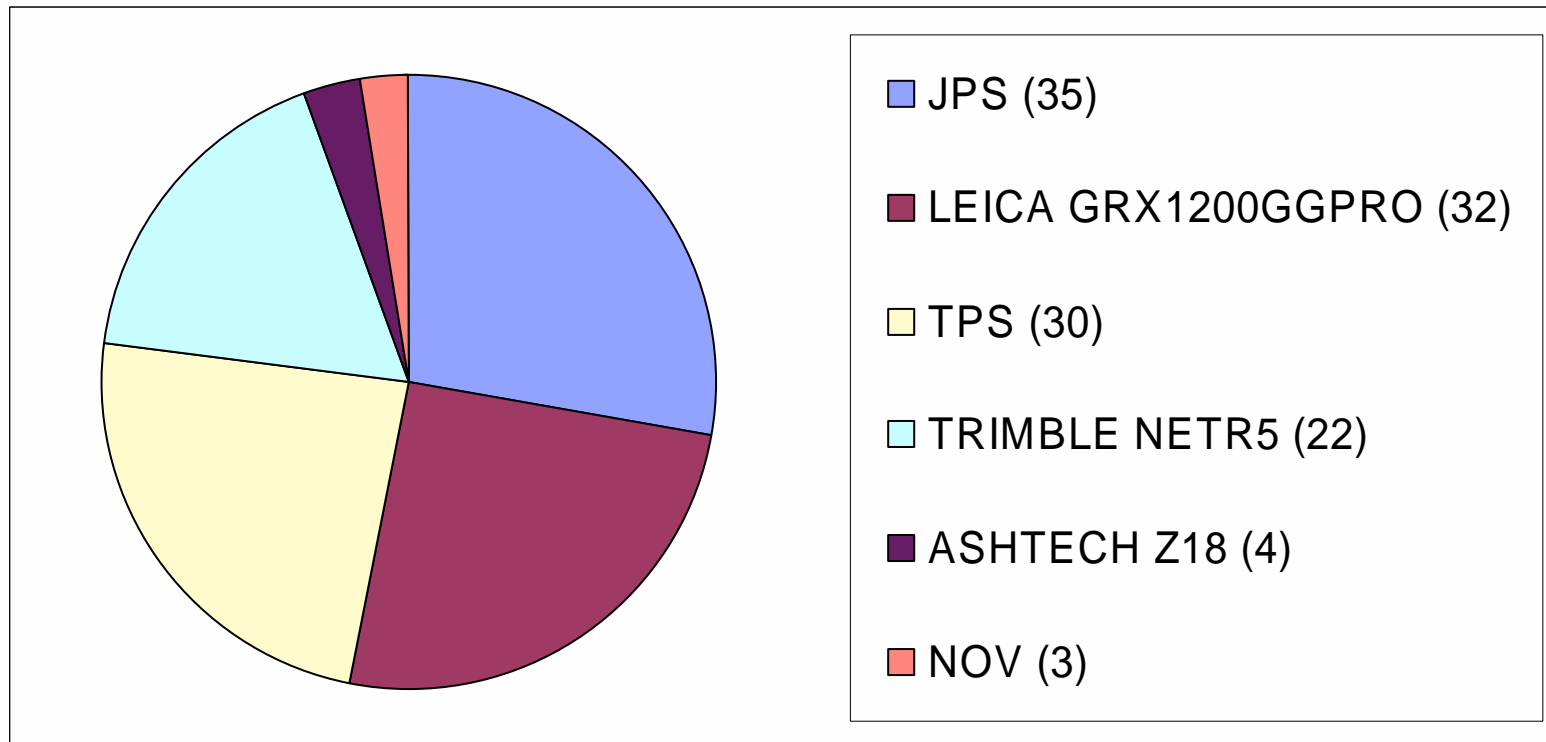
IGLOS Final Orbit Combination



<http://www.ngs.noaa.gov/igsacc/WWW/>

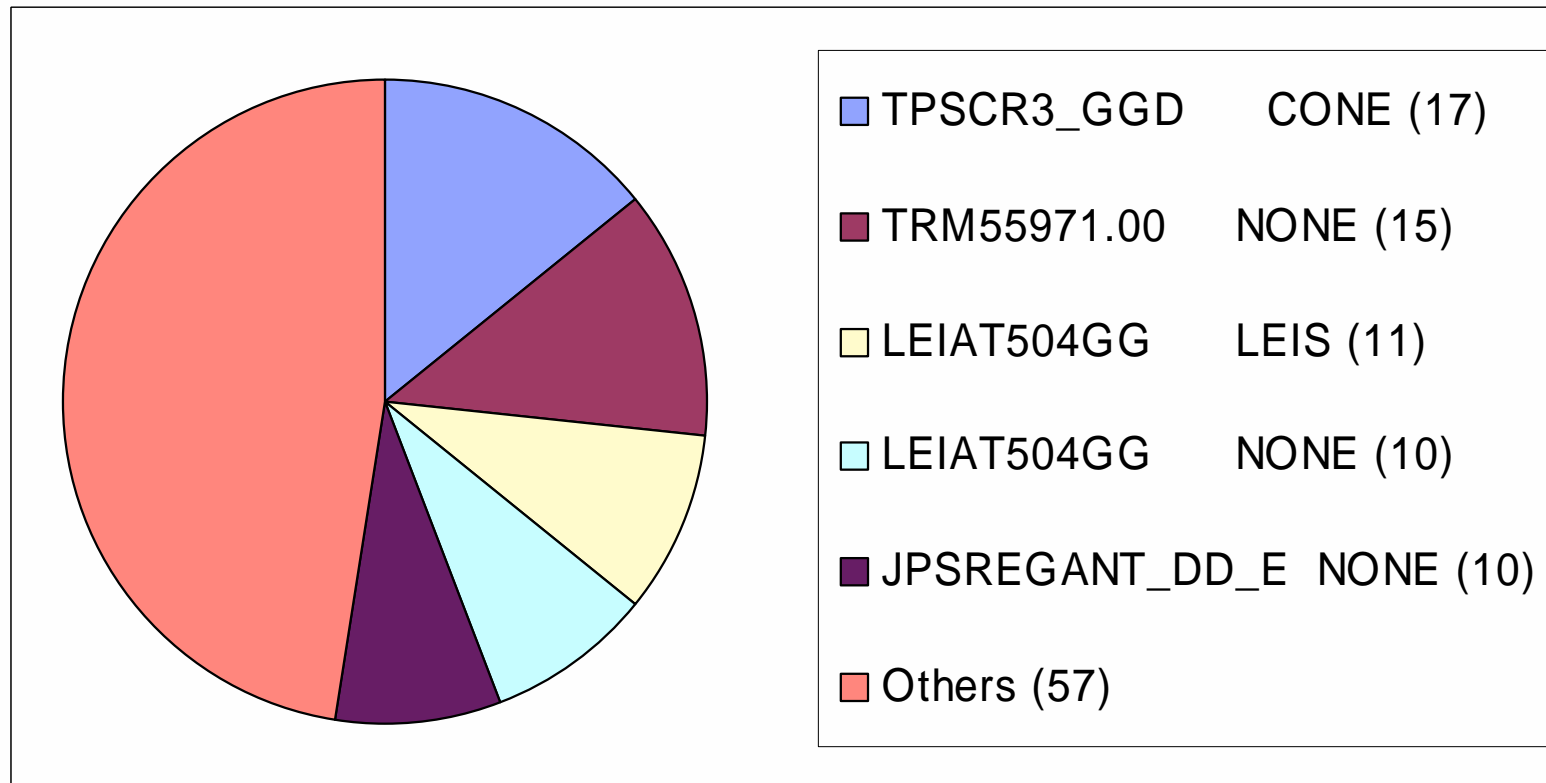


GNSS Receiver Models





GNSS Antenna/Radome Combinations





GNSS Receiver Antenna Models (1/2)

AOAD/M_B	DUTD	1	IGS05_1499	ADOPTED from NONE
AOAD/M_B	OSOD	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	AUST	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	DOVE	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	JPLA	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	NONE	4	IGS05_1499	ROBOT
AOAD/M_T	OSOD	5	IGS05_1499	ADOPTED from NONE
ASH700936C_M	SNOW	1	IGS05_1499	ROBOT
ASH700936D_M	NONE	1	IGS05_1499	ROBOT
ASH701073.1	NONE	1	IGS05_1499	COPIED
ASH701073.1	SCIS	1	IGS05_1499	ADOPTED from NONE
ASH701073.1	SNOW	1	IGS05_1499	ADOPTED from NONE
ASH701941.B	NONE	1	IGS05_1499	CONVERTED
ASH701941.B	SCIT	1	IGS05_1499	ADOPTED from NONE
ASH701941.B	SNOW	2	IGS05_1499	ADOPTED from NONE
ASH701945B_M	NONE	1	IGS05_1499	COPIED
ASH701945C_M	NONE	4	IGS05_1499	COPIED
ASH701945C_M	OSOD	1	IGS05_1499	ADOPTED from NONE
ASH701945C_M	SNOW	1	IGS05_1499	ROBOT
ASH701945E_M	NONE	2	IGS05_1499	COPIED
ASH701945G_M	AUST	1	IGS05_1499	ADOPTED from NONE
ASH701946.3	NONE	1	IGS05_1499	COPIED
JPLD/M_R	NONE	1	IGS05_1499	CONVERTED
JPSREGANT_DD_E	NONE	10	IGS05_1499	ROBOT
JPSREGANT_SD_E	NONE	5	IGS05_1499	ROBOT
LEIAT504	NONE	1	IGS05_1499	ROBOT
LEIAT504GG	LEIS	11	IGS05_1499	ROBOT
LEIAT504GG	NONE	10	IGS05_1499	ROBOT
LEIAX1202GG	NONE	3	IGS05_1499	FIELD
NOV702GG	NONE	1	IGS05_1499	ROBOT
TPSCR.G3	TPSH	1	IGS05_1499	ROBOT
TPSCR3_GGD	CONE	17	IGS05_1499	FIELD
TPSCR3_GGD	NONE	3	IGS05_1499	FIELD
TPSCR3_GGD	PFAN	1	IGS05_1499	ROBOT
TPSG3_A1	NONE	1	IGS05_1499	FIELD
TRM29659.00	NONE	4	IGS05_1499	ROBOT
TRM29659.00	TCWD	1	IGS05_1499	ROBOT
TRM29659.00	UNAV	1	IGS05_1499	FIELD
TRM55971.00	NONE	15	IGS05_1499	ROBOT



GNSS Receiver Antenna Models (2/2)

AOAD/M_B	DUTD	1	IGS05_1499	ADOPTED from NONE
AOAD/M_B	OSOD	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	AUST	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	DOME	1	IGS05_1499	ADOPTED from NONE
AOAD/M_T	JPLA	1	IGS05_1499	ADOPTED from NONE
ASH700936C_M	SNOW	1	IGS05_1499	ROBOT
ASH700936D_M	NONE	1	IGS05_1499	ROBOT
ASH701073.1	NONE	1	IGS05_1499	COPIED
ASH701073.1	SCIS	1	IGS05_1499	ADOPTED from NONE
ASH701073.1	SNOW	1	IGS05_1499	ADOPTED from NONE
ASH701941.B	NONE	1	IGS05_1499	CONVERTED
ASH701941.B	SCIT	1	IGS05_1499	ADOPTED from NONE
ASH701945B_M	NONE	1	IGS05_1499	COPIED
ASH701945C_M	OSOD	1	IGS05_1499	ADOPTED from NONE
ASH701945C_M	SNOW	1	IGS05_1499	ROBOT
ASH701945G_M	AUST	1	IGS05_1499	ADOPTED from NONE
ASH701946.3	NONE	1	IGS05_1499	COPIED
JPLD/M_R	NONE	1	IGS05_1499	CONVERTED
LEIAT504	NONE	1	IGS05_1499	ROBOT
NOV702GG	NONE	1	IGS05_1499	ROBOT
TPSCR.G3	TPSH	1	IGS05_1499	ROBOT
TPSCR3_GGD	PFAN	1	IGS05_1499	ROBOT
TPSG3_A1	NONE	1	IGS05_1499	FIELD
TRM29659.00	TCWD	1	IGS05_1499	ROBOT
TRM29659.00	UNAV	1	IGS05_1499	FIELD
ASH701941.B	SNOW	2	IGS05_1499	ADOPTED from NONE
ASH701945E_M	NONE	2	IGS05_1499	COPIED
LEIAX1202GG	NONE	3	IGS05_1499	FIELD
TPSCR3_GGD	NONE	3	IGS05_1499	FIELD
AOAD/M_T	NONE	4	IGS05_1499	ROBOT
ASH701945C_M	NONE	4	IGS05_1499	COPIED
TRM29659.00	NONE	4	IGS05_1499	ROBOT
AOAD/M_T	OSOD	5	IGS05_1499	ADOPTED from NONE
JPSREGANT_SD_E	NONE	5	IGS05_1499	ROBOT
JPSREGANT_DD_E	NONE	10	IGS05_1499	ROBOT
LEIAT504GG	NONE	10	IGS05_1499	ROBOT
LEIAT504GG	LEIS	11	IGS05_1499	ROBOT
TRM55971.00	NONE	15	IGS05_1499	ROBOT
TPSCR3_GGD	CONE	17	IGS05_1499	FIELD



Quarter-Cycle Issue: Identified Problems

- Observation codes cannot distinguish between L2(P) and L2(L2C)
- Problem because of $\frac{1}{4}$ -cycle phase shift of L2(L2C) w/r to L2(P)
 - If L2C- and P-code derived L2 phases are combined in an analysis, ambiguity-resolution can be jeopardized, if these phase shifts are not taken into account
- Need some agreement for version 2.11 how to handle this



Quarter-Cycle Issue: Controversial Discussion

- Should all phases be shifted to a common reference, if necessary, before generating RINEX files?

or

- Should all phase observations be stored in the "original" state and leave the task to do the necessary corrections to the user?
- E-Mail discussion in "RINEX group" (distribution list of ~45 addresses):
<http://www.aiub.unibe.ch/download/rinex/L2C/>



Quarter-Cycle Issue: Phase Corrections: Pros

- The receiver knows what it is doing, i.e. it knows its tracking mode.
→ It can do the corrections to an accepted standard
- The manufacturer-provided RINEX converter knows what the receiver did store in the proprietary format: The converter can do the corrections
- The user does not have to deal with these corrections. He can freely mix observables without having to bother with corrections.
- No changes to many existing programs
- Keep things simple for the user. Modern GNSS signals will be complicated enough to deal with
- If the receiver just stores what comes out of its tracking loops: Is it sure that this phase really follows the general assumptions?



Quarter-Cycle Issue: Phase Corrections: Cons

- RINEX philosophy till now: No "external" corrections to the data
- Are we sure that the corrections have been applied correctly? Or applied at all?
- How to apply a priori corrections if the RINEX converter does not know the tracking mode or the signal-generation mode of the satellite ("flex power")?
 - → Same problem, of course, holds for the users!
 - Flex power will not generate phase shifts (statement in recent presentation in Los Angeles)
- Who is setting the standards?
- What happens with the existing data?



Quarter-Cycle Issue: Phase Corrections: Current Status

- Trimble:
 - Shifts L2(L2C) by $\frac{1}{4}$ cycle
 - Correction procedure for all currently tracked signals available
- Leica/Novatel
 - Probably no corrections to L2C for the time being
- Septentrio
 - Currently no corrections for RINEX 3.0
 - Proposes to correct to standard
- RTCM: Discussions under way. Probably going for a standard
- Geo++
 - Proposes to store unchanged phases into RINEX



Quarter-Cycle Issue: Some Facts

- No corrections are necessary for a specific receiver/station if only one tracking mode per frequency for all satellites
- It's not important if all phases observed by a receiver in mode A are aligned to mode B or if all phases of mode B are aligned to mode A
 - Double-difference processing (ambiguity resolution OK)
 - Zero-difference processing (ambiguity resolution OK, if possible...)
 - PPP
- If one decides to apply corrections, do them
 - either to a commonly accepted, general standard
 - or to a "*receiver-internal standard*" in case of mixed modes



Quarter-Cycle Issue: Decision

- Should be taken by the RINEX group in the very next future
- Comments to gurtner@aiub.unibe.ch
- Hopefully in agreement with RTCM (...)

→ Correction for Bernese SW 5.0



Summary

- Current GNSS satellite constellation → GLONASS (??)
- GLONASS negative frequency channels → GNSS receiver firmware updates (and “antiquated” receiver models)
- Improved IGS GNSS receiver coverage → significantly improved GLONASS orbit quality
- Quarter-cycle issue (RINEX/RTCM) → consensus not yet reached



Baseline Vector Repeatability on the Basis of GPS-Only or GPS/GLONASS

